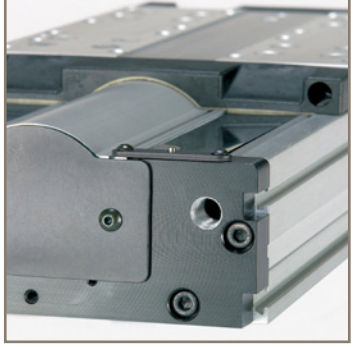


aerospace
climate control
electromechanical
filtration
fluid & gas handling
hydraulics
pneumatics
process control
sealing & shielding

XR Series
Square Rail Linear Tables

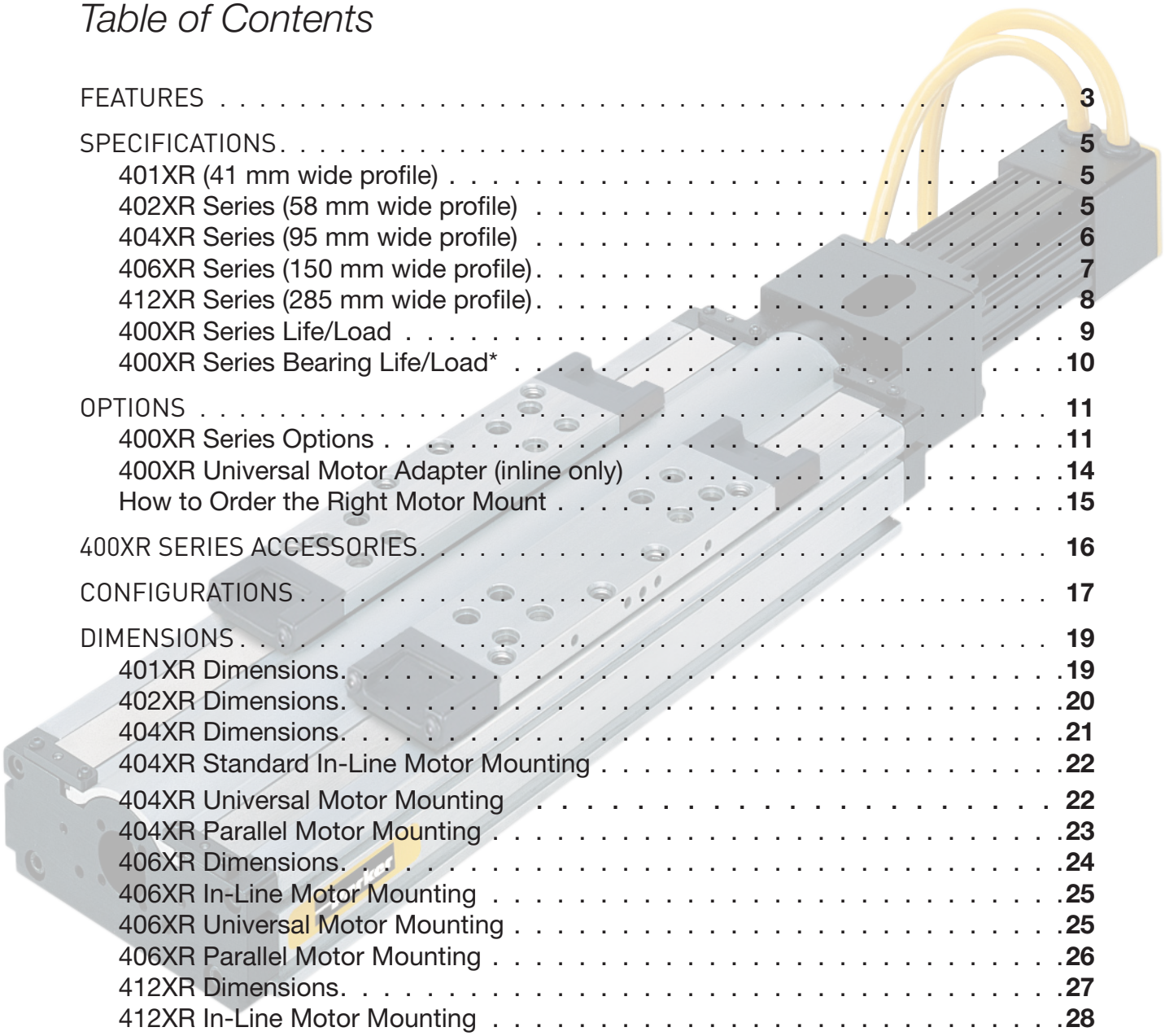
High-Precision Screw-Driven Positioners

Parker

ENGINEERING YOUR SUCCESS.

XR Series:
High-Precision Screw-Driven Positioners

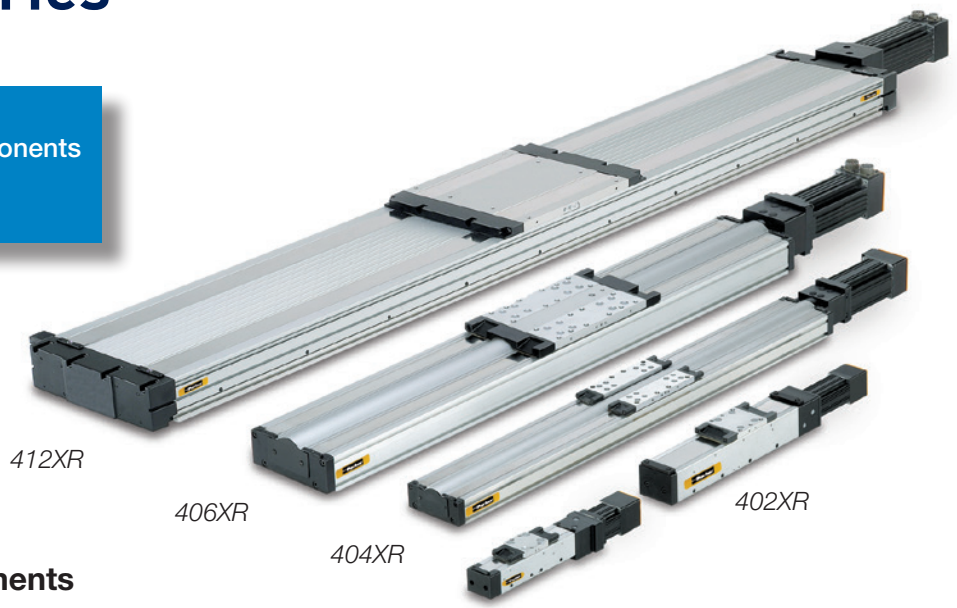
Table of Contents



FEATURES

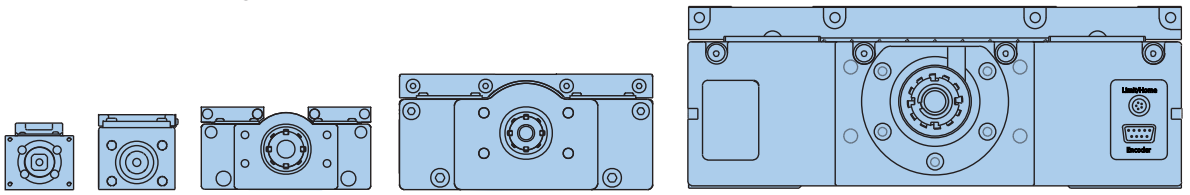
The 400XR Series

- Pre-engineered package
- Performance matched components
- Environmental protection
- Laser certified precision



Typical Enhancements

- **Limit/home position sensors**
- **Linear encoder feedback**
- **Cleanroom preparation**
- **Multi-axis brackets & adapters**
- **Numerous selectable motor mounts**
- **Servo motors and drives**
- **Programmable controls**
- **Cable management system**

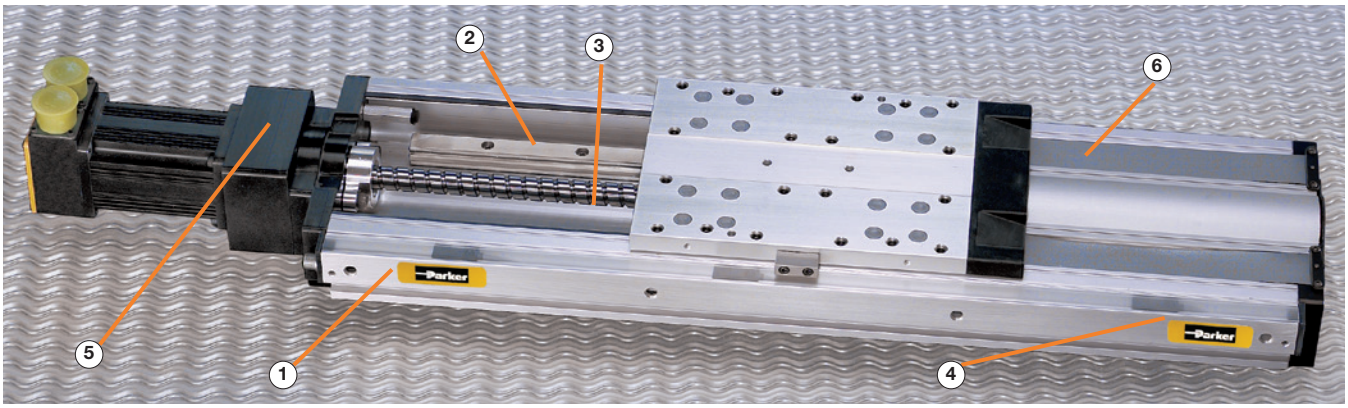


	401XR	402XR	404XR	406XR	412XR
Maximum Travel (mm)	300	600	600	2000	2000
Maximum Payload (kg)	50	100	170	630	1470
Maximum Acceleration (m/sec^2)	20	20	20	20	20

The “400XR” precision linear positioners family has achieved global recognition for consistent accuracy, reliable performance, high strength, and unmatched versatility. The XRs have excelled in industries such as life sciences, fiber optics and instrumentation, where the highest degree of precision is required.

And yet, because of the rugged construction, strength, and sealed design, these units have been used extensively for industrial automation applications (such as packaging, automotive, etc).

The XR family offers an unrivaled array of features and options which are easily matched to fit any application, from the very basic to the highly complex. Premier performance, modular compatibility, and quick delivery have made these tables the perfect building blocks for precision multi-axis systems. For examples of multiaxis systems, visit **www.parker.com/emn/XRS.**



1 High Strength Aluminum Body

Extruded aluminum housing is precision machined to provide outstanding straightness and flatness.

2 Square Rail Linear Bearing

These tables are equipped with square rail carriage support bearings which provide high load carrying capabilities, smooth precise motion and dependable performance.

3 High Efficiency Ballscrew Drive

Precision ground, or rolled ballscrew drive (5, 10, 20, 25, 32 mm lead) offers high throughput, efficiency, accuracy and repeatability.

4 Limit/Home Sensors

Proximity sensors establish “end of travel” and “home” location and are easily adjustable over entire length to restrict the travel envelope.

5 Motor Mounts

A large selection of servo and stepper motor sizes plus selectable mounting configurations (in-line, parallel) permit **hundreds** of motor mounting possibilities.

6 IP30 Rated Strip Seals

An anodized aluminum cover combined with stainless steel strip seals provide IP30 protection to interior components as well as enhance the overall appearance.

Cleanroom Preparation

Class 10 cleanroom preparation is a standard option for the 400XR series. For detailed technical information on cleanroom preparation, contact Parker’s Application Engineering Department at **1.800.245.6903**

Encoders

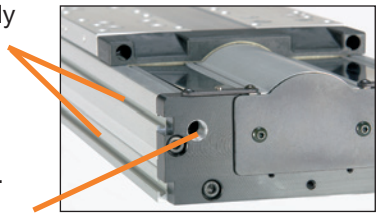
The linear encoder option offers direct positional feedback of the carriage location. The rotary shaft encoder couples directly to the drive shaft to nullify any incurred mechanical error (particularly useful with the parallel motor mount). Not shown.

Shaft Brake

The electromagnetic shaft brake option couples directly to the drive screw and is employed primarily on vertical axes to halt carriage motion during a power loss. Not shown.

Convenient Mounting Slots

Continuous T-slots along the side of the table body provide a convenient means of mounting the table to a work surface as well as mounting accessories to the table.

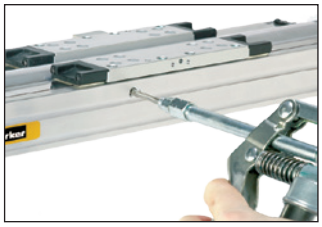


Positive Pressure Port

A standard port (1/8 NPT) for pressurizing the interior to prevent particle intrusion. (Standard on 404XR, 406XR, 412XR units.)

Easy Lube System

A standard option on some models, enables easy access for ballscrew and bearing lubrication from one access point.



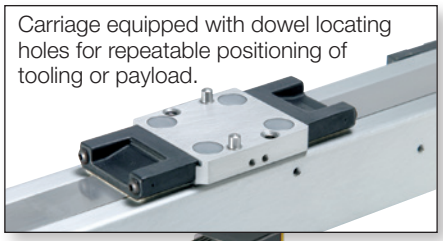
SPECIFICATIONS

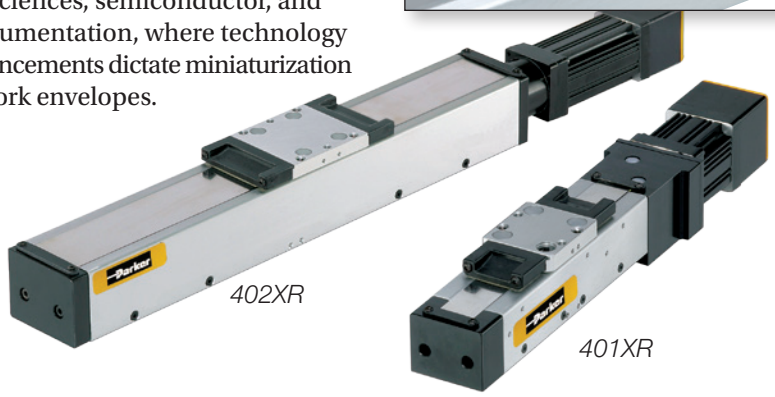
401XR (41 mm wide profile)

402XR Series (58 mm wide profile)

The 401XR and 402XR Series positioners enhance the 400XR family of precision linear positioners, addressing applications which involve precise positioning of smaller payloads within a very small space envelope.

These ballscrew driven positioners were developed to address the needs of industries such as photonics, life sciences, semiconductor, and instrumentation, where technology advancements dictate miniaturization of work envelopes.





Common Specifications

		Precision*		Standard	
		401XR	402XR	401XR	402XR
Bidirectional Repeatability 2 mm lead 5 or 10 mm lead	µm	 ±1.3 ±1.3	 – ±1.3	 ±5 ±12	 – ±12
Duty Cycle	%	100	100	100	100
Maximum Acceleration	m/sec² (in/sec²)	20 (773)	20 (773)	20 (773)	20 (773)
Normal Load Capacity (1)	kgf (lbs)	50 (110)	100 (220)	50 (110)	100 (220)
Axial Load Capacity (1) 2 mm lead 5 or 10 mm lead	kgf (lbs)	 5.5 (12.1) 15.5 (34.2)	 – 38 (84)	 5.5 (12.1) 15.5 (34.2)	 – 38 (84)
Drive Screw Efficiency	%	80	80	80	80
Maximum Breakaway Torque	Nm (in-oz)	0.03 (4.2)	0.086 (12.0)	0.03 (4.2)	0.086 (12.0)
Maximum Running Torque (2)	Nm (in-oz)	0.028 (4.0)	0.08 (11.3)	0.028 (4.0)	0.08 (11.3)
Linear Bearing Coefficient of Friction		0.01	0.01	0.01	0.01
Ballscrew Diameter 2 mm lead 5 or 10 mm lead	mm	 6 8	 – 12	 6 8	 – 12
Carriage Weight	kg (lbs)	0.045 (0.1)	0.11 (0.25)	0.045 (0.1)	0.11 (0.25)

* Requires linear encoder option E3 or E4. (1) Refer to life load charts found later in this section. (2) Ratings established at 2 rps.

Travel/Screw Lead Dependent Specifications

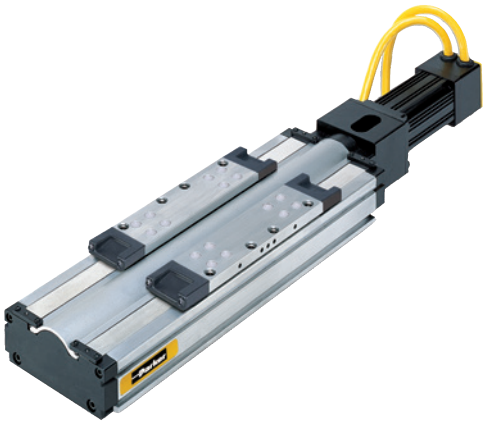
Travel (mm)	Positional Accuracy* (µm) 401XR		Positional Accuracy* (µm) 402XR		Straightness & Flatness		Input Inertia (10^{-5} kg-m²) 401XR		Input Inertia (10^{-5} kg-m²) 402XR		Max Screw Speed (revs/sec)		Unit Weight (kg)	
	Precision	Standard	Precision	Standard	401XR	402XR	2 mm	10 mm	5 mm	10 mm	401XR	402XR	401XR	402XR
50	10	20	–	–	20	–	0.6	–	–	–	100	–	1.0	–
100	10	20	10	20	20	20	0.9	–	12.0	–	100	90	1.2	2.3
150	12	20	12	20	20	20	1.1	–	15.0	–	100	90	1.3	2.6
200	16	30	16	30	25	25	–	4.7	20.0	–	100	90	1.5	2.8
300	18	40	18	40	25	25	–	5.2	–	25.0	100	90	1.7	3.2
400	–	–	21	40	–	30	–	–	–	29.0	–	95	–	3.8
600	–	–	25	50	–	30	–	–	–	39.0	–	50	–	4.8

*Consult factory for higher accuracy capabilities via slope correction or stage mapping via laser interferometry.

404XR Series (95 mm wide profile)

The 404XR is a sleek compact positioner (47.3 x 95 mm profile) capable of carrying 170 kg loads up to a distance of 600 mm. Its quick and accurate positioning capability can be attributed to a high strength extruded housing, square rail ball bearing system, and precision ground ballscrew drive.

With its low profile design the 404XR is ideal for height restricted applications, and its lightweight construction makes it well suited as secondary axes on multi-axis systems. These units offer a wide array of easily adapted options and accessories which permit easy configuration to specific requirements.



Common Specifications

		Precision	Standard
Bidirectional Repeatability (5) Ballscrew Leadscrew	µm	±1.3 —	±3 ±12
Duty Cycle Ballscrew Leadscrew	%	100 –	100 75
Maximum Acceleration	m/sec² (in/sec²)	20 (773)	20 (773)
Normal Load Capacity (1)	kgf (lbs)	170 (375)	170 (375)
Axial Load Capacity (2) Ballscrew Leadscrew	kgf (lbs)	90 (198) –	90 (198) 25 (55)
Drive Screw Efficiency Ballscrew Leadscrew	%	90 30	90 30
Maximum Breakaway Torque	Nm (in-oz)	0.13 (18)	0.18 (26)
Maximum Running Torque (3)	Nm (in-oz)	0.11 (16)	0.17 (24)
Linear Bearing Coefficient of Friction		0.01	0.01
Screw Diameter Ballscrew Leadscrew	mm	16 —	16 12.7
Carriage Weight	kg (lbs)	0.70 (1.55)	0.70 (1.55)

Parallel Motor Mount
(with limit/home sensor pack option)

(1) Refer to life load charts found later in this section.
(2) Axial load for parallel mount is limited by a maximum input torque of 2.5 Nm.
(3) Ratings established at 2 rps.
(4) Consult factory for higher accuracy capabilities via slope correction or stage mapping via laser interferometry.
(5) Consult factory for specifications with linear encoder.
(6) Consult factory for higher screw speeds.

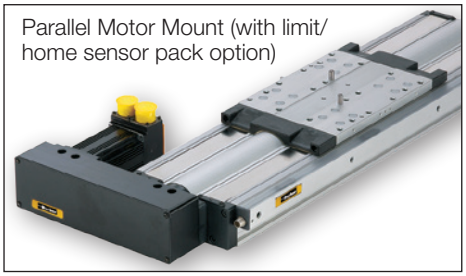
Travel/Screw Lead Dependent Specifications

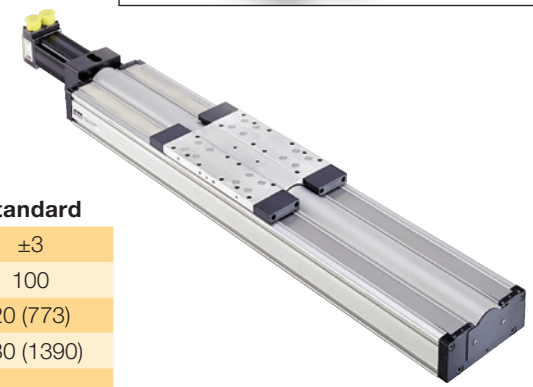
Travel (mm)	Positional Accuracy (4) (5) (µm)			Straightness & Flatness		Input Inertia (10^{-5} kg-m²)			Max Screw Speed (6) (revs/sec)		Unit Weight (kg)
	Ballscrew		Leadscrew								
	Precision	Standard		Ballscrew	Leadscrew	5 mm	10 mm	20 mm	Ballscrew	Leadscrew	
50	8	12	20	6	8	1.68	1.81	2.34	60	25	2.8
100	8	12	20	6	8	1.93	2.07	2.60	60	25	3.0
150	10	14	30	9	12	2.19	2.32	2.85	60	25	3.3
200	12	20	40	10	16	2.44	2.57	3.11	60	25	3.6
250	12	22	50	12	16	2.69	2.83	3.36	60	25	3.9
300	14	24	60	13	18	2.95	3.08	3.61	60	25	4.2
350	14	26	70	15	23	3.20	3.33	3.87	60	25	4.5
400	16	26	80	16	27	3.46	3.59	4.12	60	25	4.8
450	19	28	90	18	30	3.71	3.84	4.37	60	25	5.1
500	21	34	100	19	30	3.96	4.10	4.63	60	20	5.4
550	23	36	110	21	30	4.22	4.35	4.88	60	20	5.7
600	25	40	112	22	30	4.47	4.60	5.14	54	20	6.0

406XR Series (150 mm wide profile)

The 406XR can position high loads (up to 630 kgf) over distances up to two meters. Because of its size and strength (270 Nm, 200 lb-ft moment load capacity) this durable table is ideal as the base unit in a multi-axis system.

From high resolution to high throughput, selectable ballscrew leads (5, 10, 20, 25 mm) make the desired resolution/velocity ratio easy to achieve, and stainless steel seal strips alleviate environmental concerns.


Parallel Motor Mount (with limit/ home sensor pack option)



Common Specifications

		Precision	Standard
Bidirectional Repeatability (5)	µm	±1.3	±3
Duty Cycle	%	100	100
Maximum Acceleration	m/sec² (in/sec²)	20 (773)	20 (773)
Normal Load Capacity (1)	kgf (lbs)	630 (1390)	630 (1390)
Axial Load Capacity (2) 0 to 600 mm Travel 700 to 2000 mm Travel	kgf (lbs)	90 (198) –	90 (198) 200 (440)
Drive Screw Efficiency	%	90	90
Maximum Breakaway Torque 0 to 600 mm Travel 700 to 2000 mm Travel	Nm (in-oz)	0.13 (18) –	0.18 (26) 0.39 (55)
Maximum Running Torque (3) 0 to 600 mm Travel 700 to 2000 mm Travel	Nm (in-oz)	0.11 (16) –	0.17 (24) 0.34 (48)
Linear Bearing Coefficient of Friction		0.01	0.01
Ballscrew Diameter 0 to 600 mm Travel 700 to 2000 mm Travel	mm	16 –	16 25
Carriage Weight	kg (lbs)	2.7 (5.94)	2.7 (5.94)

(1) Refer to life load charts found later in this section.
(2) Axial load for parallel mount is limited to: 140 lbs for the 5, 10 and 20 mm lead drives:
104 kg (230 lbs) for 25 mm lead drives
(3) Ratings established at 2 rps.
(4) Consult factory for higher accuracy capabilities via slope correction or stage mapping via laser interferometry.
(5) Consult factory for specifications with linear encoder.
(6) Consult factory for higher screw speeds.

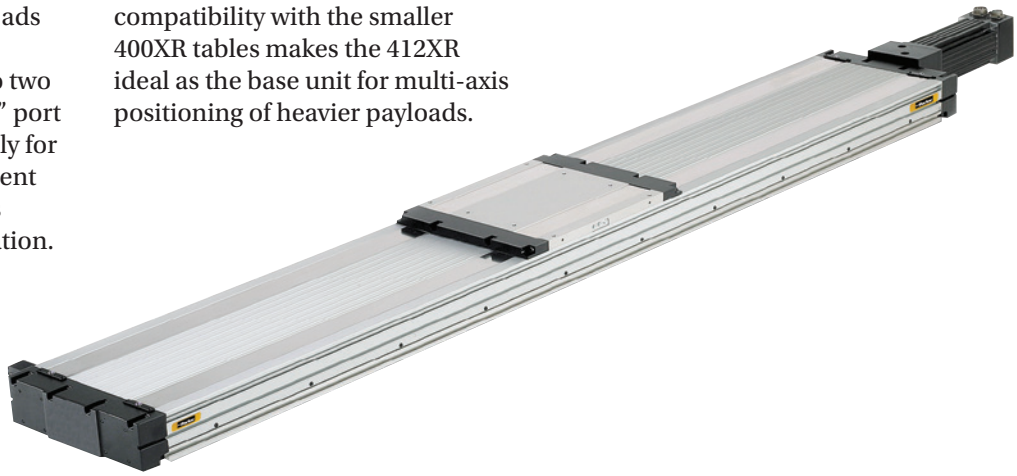
Travel/Screw Lead Dependent Specifications

Travel (mm)	Positional Accuracy (4) (5) (µm)		Straightness & Flatness	Input Inertia (10^{-5} kg-m²)				Max Screw Speed (6) (revs/sec)	Unit Weight (kg)
	Precision	Standard		5 mm	10 mm	20 mm	25 mm		
100	8	12	6	3.34	3.85	5.90	–	60	8.7
200	12	20	10	3.92	4.43	6.48	–	60	10.0
300	14	24	13	4.50	5.01	7.06	–	60	11.3
400	16	26	16	5.08	5.59	7.64	–	60	12.6
500	21	34	19	5.65	6.17	8.22	–	55	13.9
600	25	40	22	6.23	6.75	8.80	–	44	15.2
700	–	92	25	36.51	37.02	–	40.61	47	19.2
800	–	94	29	39.96	40.47	–	44.07	47	20.7
900	–	103	32	43.41	43.93	–	47.52	47	22.2
1000	–	105	35	46.87	47.38	–	50.97	47	23.7
1250	–	118	42	55.50	56.01	–	59.61	35	27.6
1500	–	134	50	64.14	64.65	–	68.24	26	31.4
1750	–	154	57	72.77	73.28	–	76.88	20	35.2
2000	–	159	65	81.40	81.92	–	85.51	16	39.1

412XR Series (285 mm wide profile)

The 412XR is a rugged heavy duty linear table (285 mm x 105 mm profile) that enables massive loads (up to 1470 kgf) to be precisely positioned over distances up to two meters. Single point "easy lube" port is standard on carriage assembly for simple servicing and a convenient adapter plate (#100-6784-01) is available for easy X-Y configuration.

An unrivaled array of options combined with mounting compatibility with the smaller 400XR tables makes the 412XR ideal as the base unit for multi-axis positioning of heavier payloads.



Common Specifications

		Standard	
Screw Lead	mm	5, 10, 25	32
Bidirectional Repeatability (4)	µm	±5	±5
Duty Cycle	%	100	100
Maximum Acceleration	m/sec^2 (in/sec^2)	20 (773)	20 (773)
Normal Load Capacity (1)	kg (lbs)	1470 (3241)	1470 (3241)
Axial Load Capacity	kg (lbs)	200 (441)	460 (1014)
Drive Screw Efficiency	%	90	80
Maximum Breakaway Torque	Nm (in-oz)	0.61 (86)	0.76 (108)
Maximum Running Torque (2)	Nm (in-oz)	0.55 (78)	0.69 (98)
Linear Bearing Coefficient of Friction		0.01	0.01
Ballscrew Diameter	mm	25	32
Carriage Weight	kg (lbs)	12 (27)	13 (28)

(1) Refer to life load charts found later in this section.
(2) Ratings established at 2 rps.
(3) Consult factory for higher accuracy capabilities via slope correction or stage mapping via laser interferometry.
(4) Consult factory for specifications with linear encoder.
(5) Consult factory for higher screw speeds.

Travel/Screw Lead Dependent Specifications

Travel (mm)	Positional Accuracy (3) (4) (µm)	Straightness & Flatness	Input Inertia (10^{-5} kg-m^2)				Max Screw Speed (5) (revs/sec)		Unit Weight (kg)	
			5 mm	10 mm	25 mm	32 mm	5, 10, 25 mm	32 mm	5, 10, 25 mm	32 mm
150	64	9	27.20	29.45	46.76	98.20	47	42	39.6	41.5
250	66	12	30.21	32.46	49.78	106.28	47	42	42.9	45.0
350	71	15	33.23	35.48	52.79	114.37	47	42	46.2	48.5
650	91	24	42.27	44.52	61.83	138.63	47	42	56.1	59.0
800	94	29	46.79	49.04	66.35	150.76	47	42	61.0	64.2
1000	105	35	52.81	55.06	72.37	166.94	45	42	67.6	71.2
1250	118	42	58.84	61.09	78.40	183.11	34	41	74.2	78.2
1500	134	50	67.87	70.12	87.44	207.38	24	31	84.1	88.7
1750	154	57	75.41	77.66	94.97	227.59	18	24	92.4	97.5
2000	159	65	82.94	85.19	102.50	247.81	15	19	100.6	106.2

400XR Series Life/Load

The following performance information is provided as a supplement to the product specifications pages. The following graphs are used to establish the table life relative to the applied loads.

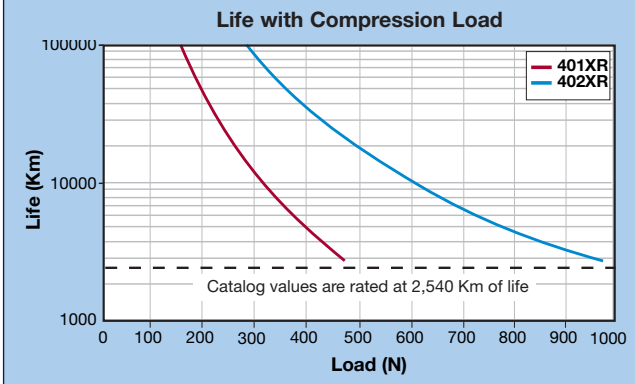
The useful life of a linear table at full catalog specifications is dependent on the forces acting upon it. These forces include both static components resulting from payload weight, and dynamic components due to acceleration/deceleration of the load. In multi-axes applications, the primary positioner at the bottom of the stack usually establishes the load limits for the combined axes. When determining life/load, it is critical to include the weight of all positioning elements that contribute to the load supported by the primary axis.

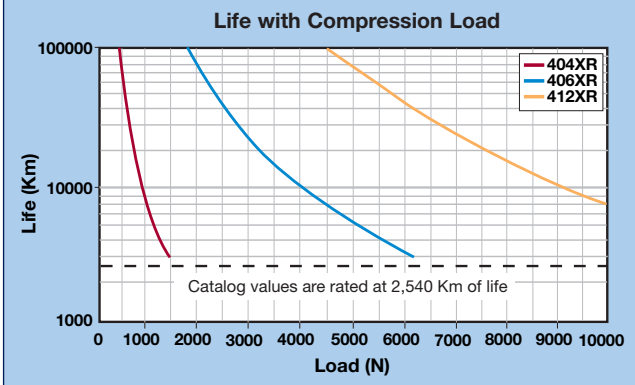
Catalog load specifications are rated for 100 million inches of travel or 2,540 km.

For final evaluation of life vs load, including off center, tension, and side loads, refer to the charts and formulas found on our web site at **www.parker.com/emn/400XR.**

Normal Load (Compression)

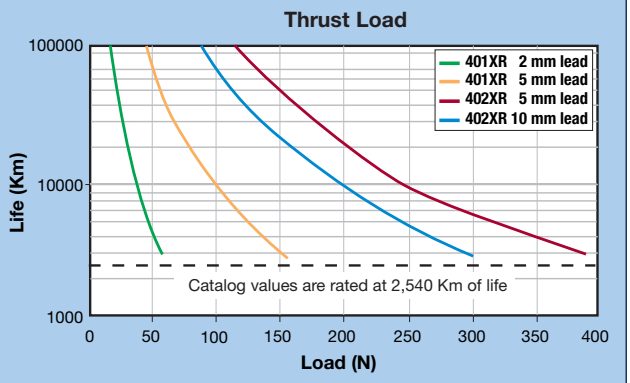
These graphs provide a "rough cut" evaluation of the support bearing life/load characteristics. The curves show the life/load relationship when the applied load is centered on the carriage, normal (perpendicular) to the carriage mounting surface.

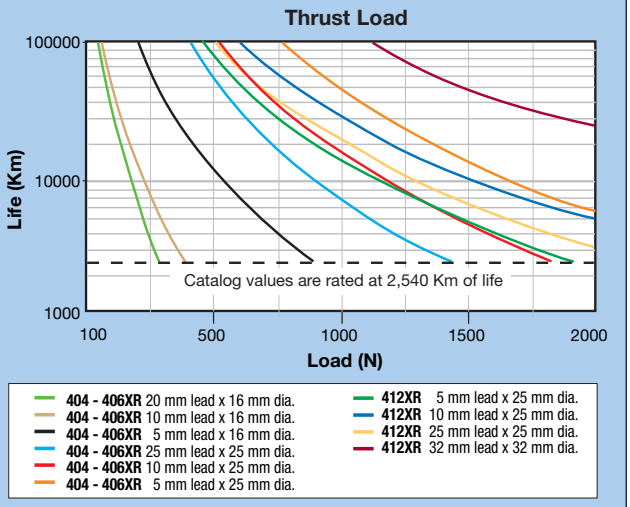




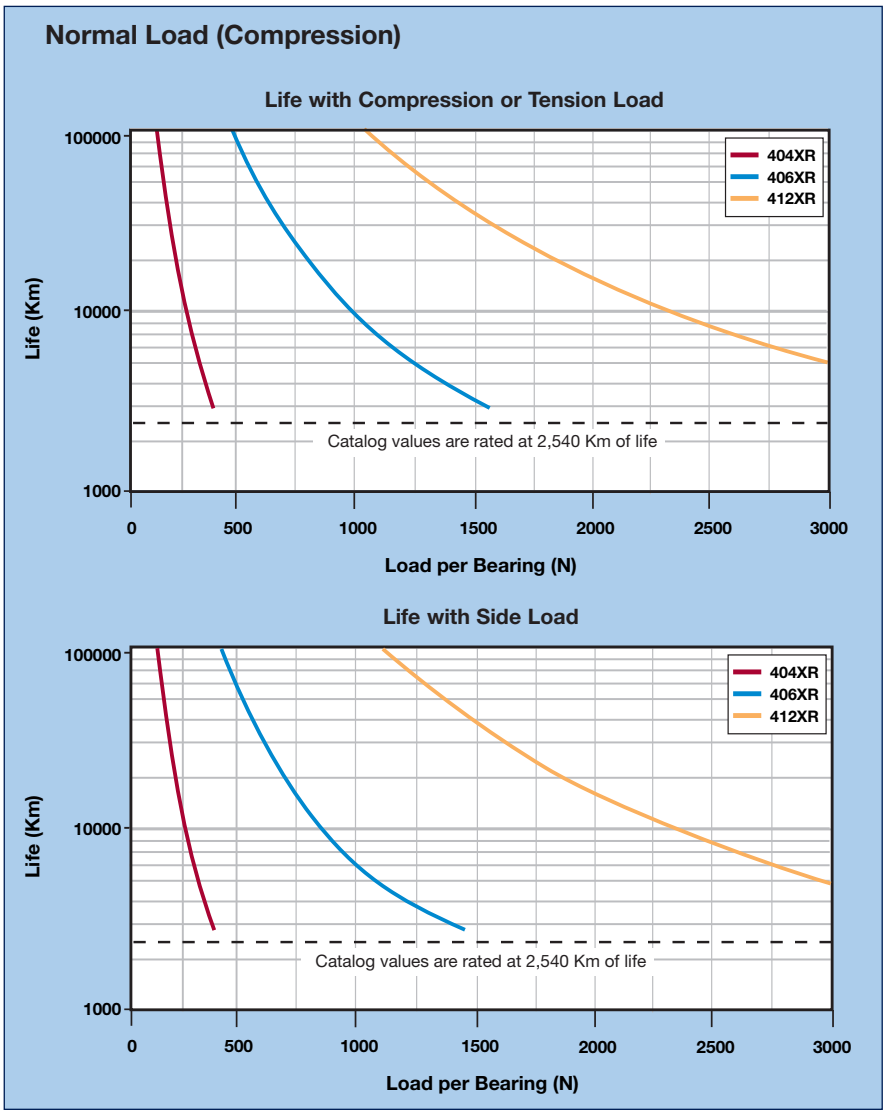
Axial Load (Thrust)

These graphs illustrate table ballscrew life relative to the axial load.





400XR Series Bearing Life/Load*



*For 401XR and 402XR moment loading capacities, please refer to the maintenance manual.

These charts are to be used in conjunction with the corresponding formulas found in the product manuals at www.parkermotion.com to establish the life/load for each bearing (4 per table).

Several dimensions, which are specific to each linear positioning table model, and the load geometry are required for these computations. These dimensions are supplied in the catalog information for each positioner. The dimensions are referenced as follows:

d1 bearing block center-to-center longitudinal spacing
d2 bearing rail center-to-center lateral spacing
da Rail center-to-carriage mounting surface

	d1	d2	da
404XR	80	57	28
406XR	114	90.3	42.5
412XR	205	192	43

Refer to Parker's website www.parker.com/emn/400XR for moment loading and other engineering data.

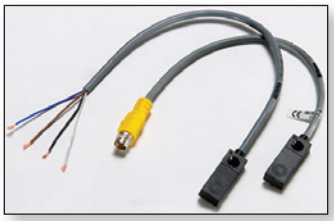
OPTIONS

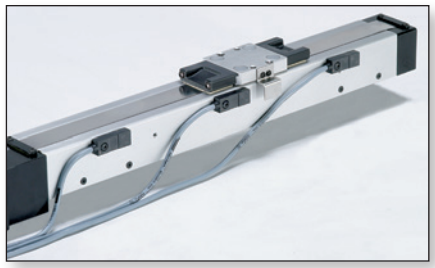
400XR Series Options

Home or Limit Sensor Options

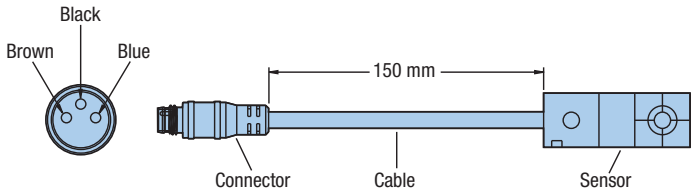
End of Travel and Home Sensors for the 400XR series are available in a variety of styles. The sensors can be ordered as part of the table or as separate components with the associated mounting hardware or in an enclosed sensor pack. A 5 meter high-flex extension cable (Part No. 003-2918-01) is included for use with the 401XR thru 406XR models having the locking connector option.

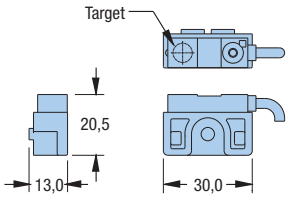
- NPN (Sinking) or PNP (Sourcing)
- Normally Closed (N.C.) or Normally Open (N.O.)
- Flying Leads or Locking Connector





401XR Limits and Home Sensor





Sensor / Bracket Detail

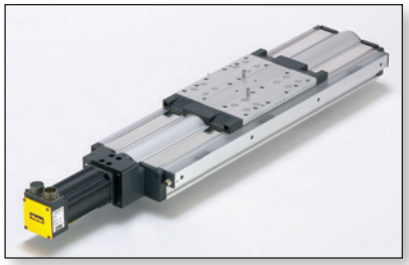
Specifications

Input Power	5-30 VDC, 20 mA
Output	100mA max
Wire Color	(+) Supply: Brown
Code	(–) Supply: Blue NO Output: Black NC Output: White

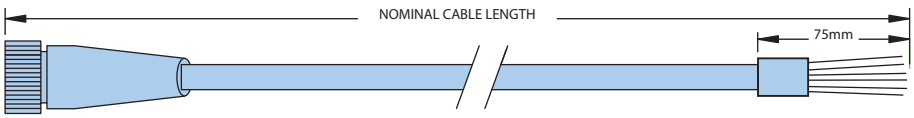
Order Code	Part Number*	Switch Type	Logic	Cable Length	Connector Option
H2 or L2	006-1639-01	N.C.	Sinking	3.0 m	Flying Leads
H3 or L3	006-1639-02	N.O.	Sinking	3.0 m	Flying Leads
H4 or L4	006-1639-03	N.C.	Sourcing	3.0 m	Flying Leads
H5 or L5	006-1639-04	N.O.	Sourcing	3.0 m	Flying Leads
H6 or L6	006-1639-09	N.C.	Sinking	150 mm	Locking Connector
H7 or L7	006-1639-08	N.O.	Sinking	150 mm	Locking Connector
H8 or L8	006-1639-11	N.C.	Sourcing	150 mm	Locking Connector
H9 or L9	006-1639-10	N.O.	Sourcing	150 mm	Locking Connector
H11 or L11	See chart below	N.C.	Sinking	See chart below	Sensor Pack
H12 or L12	See chart below	N.O.	Sinking	See chart below	Sensor Pack
H13 or L13	See chart below	N.C.	Sourcing	See chart below	Sensor Pack
H14 or L14	See chart below	N.O.	Sourcing	See chart below	Sensor Pack

* Applies to 401XR thru 406XR models. 412XR models have limits and homes internally mounted with a connector termination. Sensor triggers (targets) ordered separately.

Sensor Pack Cable



406XR with Limit and Home Sensor Pack



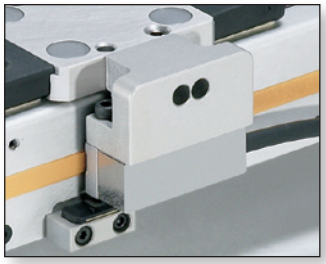
Description	Part Number
3 Meters	006-1742-01
7.5 Meters	006-1742-02

Wire Color	Function	Pin Number
Red	+5 to +24 VDC	A
Blue	Limit 1 (LXR –)	B
Orange	Limit 2 (LXR +)	C
Green	Home	D
Black	Ground	E
Green/Yellow	Shield	Shield Case

Linear Encoder Options (Tape Scale)

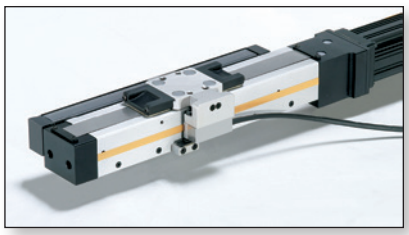
A linear position feedback device which mounts directly to the table carriage. (Factory installation required.)

- 1.0 µm resolution
- 0.5 µm resolution
- 0.1 µm resolution



Specifications

Input Power	5 VDC, 150mA
Output	A/B quadrature and reference mark, differential line drive output
Resolution	1.0, 0.5, 0.1 micron
Cable Length	3 m



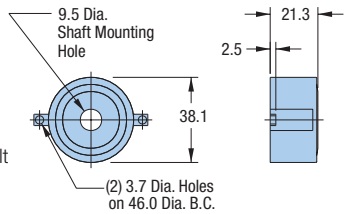
401XR with Linear Encoder plus Sensor Pack

Rotary Encoder Option

Modular rotary encoder couples directly to the drive screw for position feedback and is easily field installed. The rotary encoder cannot be installed with the brake assembly option.

- 5000 counts/rev

Note: Dimensions shown apply to 404XR and 406XR models. Consult factory for 412XR dimensions.

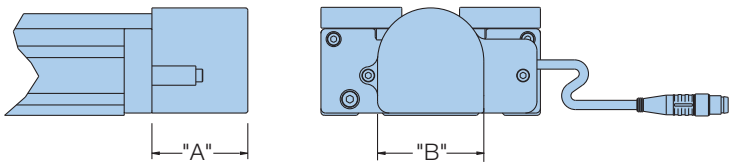


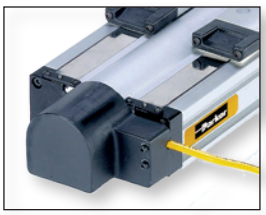
Specifications

Input Power	5 VDC, 135 mA
Output	A/B quadrature and reference mark, differential line drive output
Resolution	1250 lines/rev equals 5000 counts post quadrature (1 µm with 5 mm lead ballscrew)
Cable Length	150 mm

Brake Assembly Option

Electromagnetic brake assembly used to prevent "backdriving" in vertical applications. The brake option includes a 5 m extension cable. The brake option is easily field installed. The brake option cannot be installed with the rotary encoder option.





404XR with Brake Option

Table Series	Part Number	Input Power	Holding Torque	Dimensions (mm) A	Dimensions (mm) B
401XR/402XR	—	—	—	—	—
404XR	006-1627-01	24 VDC, 0.46 A	2.0 Nm	41.5	46.0
406XR	006-1656-01	24 VDC, 0.5 A	4.5 Nm	49.9	57.5
412XR	002-1916-01	24 VDC, 0.75 A	9.0 Nm	54.0	72.0

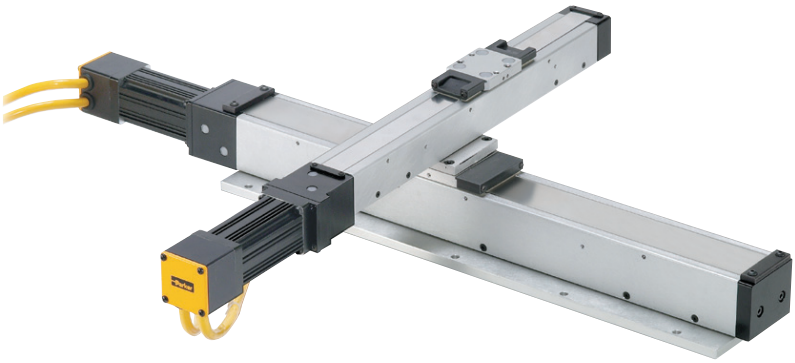
Dowel Pinning Options*

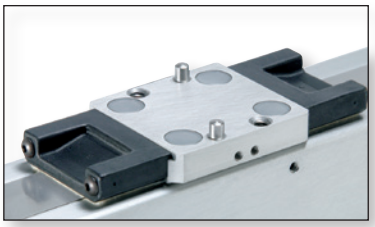
Standard dowel pin locating holes are offered on most 400XR units to facilitate repeatable mounting of tooling or payload.*

In addition, pinning options are offered for precise orthogonal mounting of the second axis in a multi-axis system. In this case, the bottom side of the table base is match drilled and reamed to the first axis to provide exact orthogonal location.

This convenient option eliminates concerns regarding contamination or damage often associated with machining for locating pins in an assembled unit.

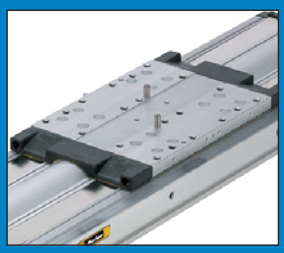
*Not available with 401XR or 402XR or 50 mm travel 404XR.





Two locating dowel pins shown in carriage of a 401XR.

Standard pinning of XY axes will achieve 125 arc-sec of orthogonality. Through transfer pinning, 30 arc-sec is achievable. For high degrees of orthogonality consult the factory.



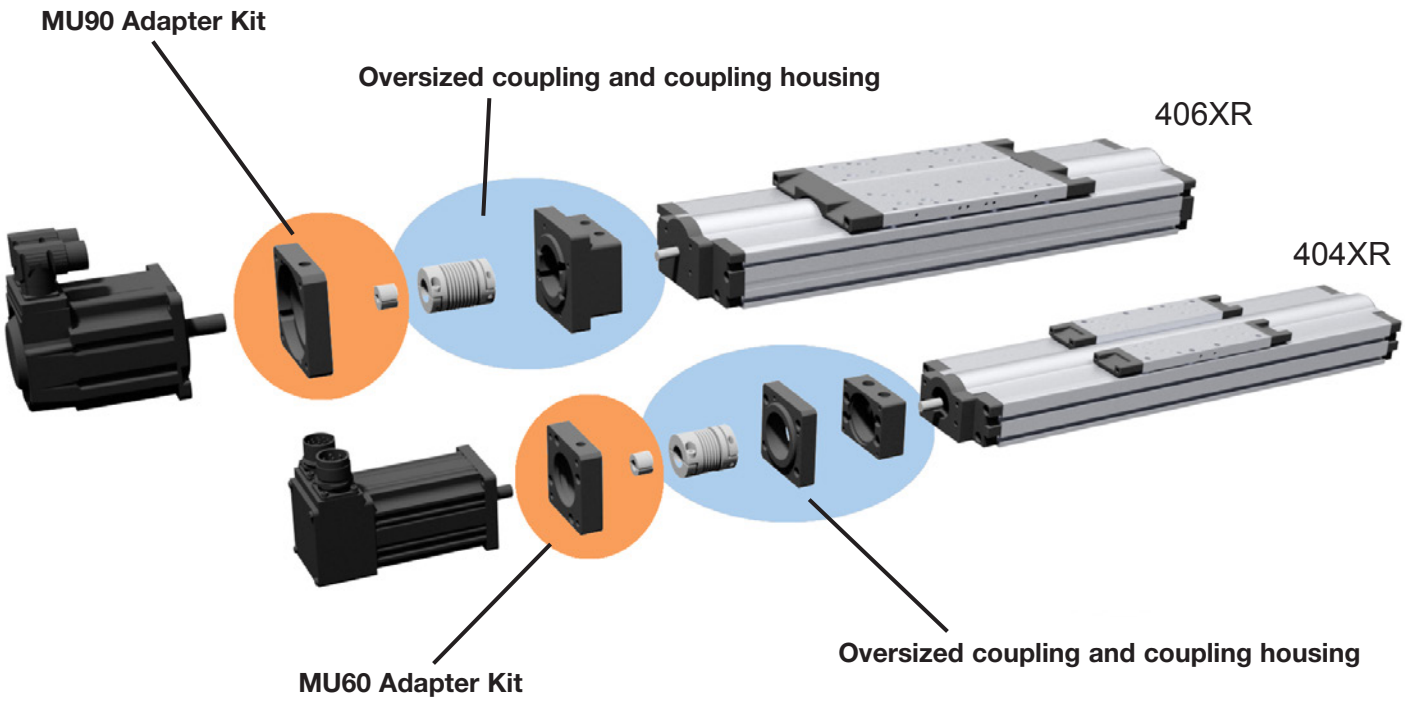
400XR Universal Motor Adapter (inline only)

The UMA is designed to make it easier than ever for our machine designers to specify their linear stage with whatever motor they'd like, while avoiding the often drawn out "customization" process.

Quick Motor Integration
The Universal Motor Adapter (UMA) is an innovative motor mount component that allows for simple configuration of the 404XR or 406XR to a variety of servo or steppers from a plethora of manufacturers. Utilizing a vast database of motor mounting flanges, the UMA allows for rapid integration of hundreds of motors from numerous manufacturers.

Convenient Ordering
For customers choosing to mount a third party, non-Parker motor, the UMA alleviates the hassle and lead time of having to create a "customized" motor mount. Typically, designers would have to place an additional custom motor request for a specific mount, but now designers can simply configure the motor manufacturer right into the XR part number

Easy Selection with Our Online e-Configurator
Now with the UMA, you can easily choose the right option for your motor through our online e-Configurator, saving time and money. With the UMA integrated into the e-Configurator, simply selecting the desired motor manufacturer and model type will configure the actuator with the appropriate selected motor.

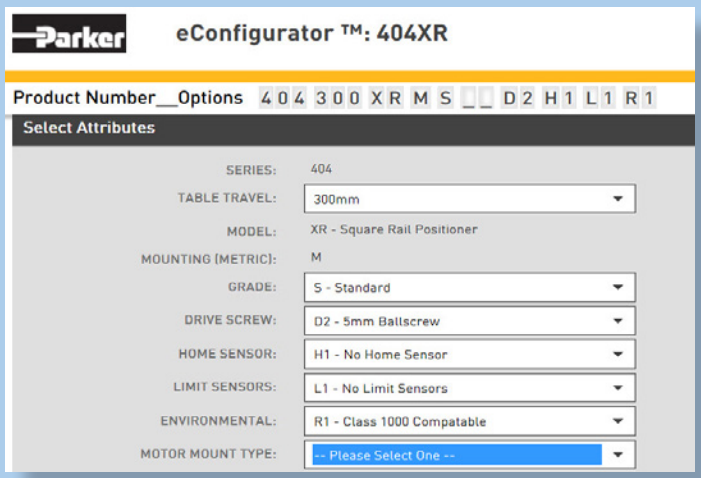


How to Order the Right Motor Mount

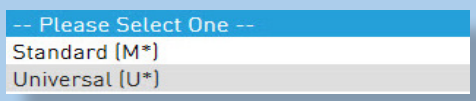
Motor mount configuration to 3rd party motors is now easier than ever through use of the universal motor adapter (UMA), and our online product configuration tool. Consult the online e-Configurator for a complete listing of supported motors.

If you do not find a specific motor you would like use in your application, please call our application's team at 1-800-358-9070.

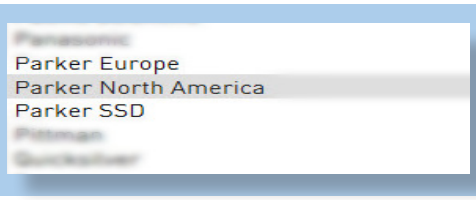
STEP 1
In order to specify a 404 or 406 XR with a third party motor mount, launch the online configurator tool from **www.parker.com/emn/400XR** and for the appropriate 404 or 406 XR.



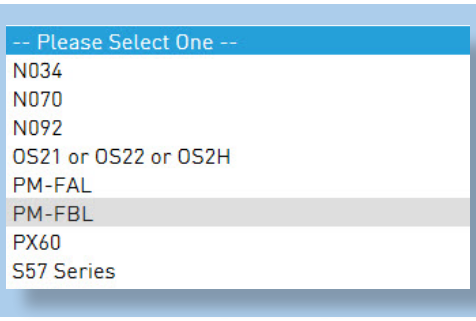
STEP 2
Configure the XR with all desired options and then specify the motor mount type. Select Standard for Parker Motors or Universal for other motors.



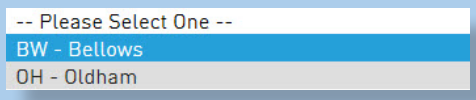
STEP 3
Select the motor manufacturer.



STEP 4
After motor manufacturer, choose the exact motor series from that manufacturer. This will automatically select the appropriate motor mount for the 400 XR stage.



STEP 5
Finally, select from either Bellows or Oldham style coupling options.



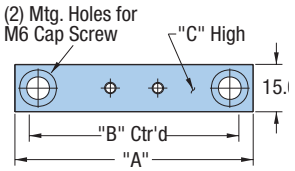
400XR SERIES ACCESSORIES

Riser Plate Accessory

Used to raise the table base to provide clearance for motors.

Model	Part Number
401XR	002-2063-01
402XR	002-2064-01
404XR	002-3619-01
406XR	002-3625-01
412XR	—

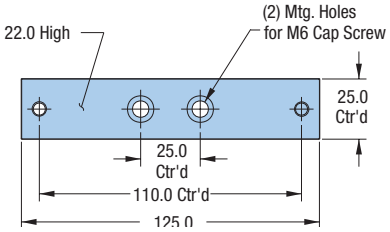
401XR/402XR
Part Number: 002-2063-01/ 002-2064-01



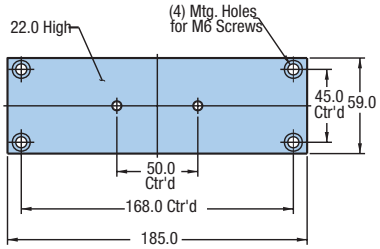
Dimensions (mm)

Table Series	A	B	C
401XR	65.0	50.4	17.0
402XR	90.0	75.4	10.0

404XR
Part Number: 002-3619-01



406XR
Part Number: 002-3625-01

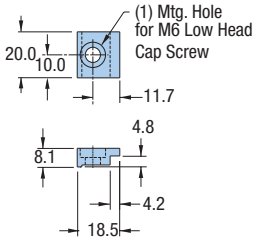


Toe Clamp Accessory

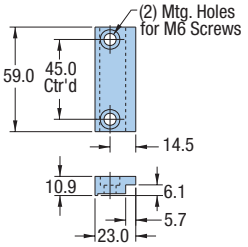
Used for convenient outboard mounting of table to a base plate, riser plates, Z-axis bracket, or other 400XR table. All hardware is included.

Model	Part Number
404XR	002-3618-01
406XR	002-3624-01
412XR	002-2160-01

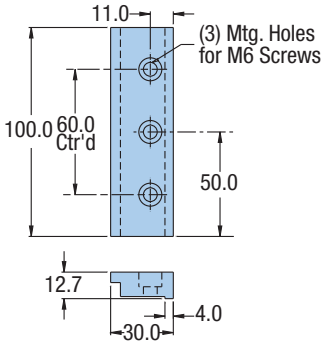
404XR
Part Number: 002-3618-01



406XR
Part Number: 002-3624-01



412XR
Part Number: 002-2160-01



CONFIGURATIONS

400XR Multi-Axis Cartesian Robot Configurations

Base Axis (X) *	Orientation	Second Axis (Y or Z)* 401XR 50 mm	401XR >50 mm	402XR	404XR	404LXR	406XR	406LXR	412XR 412LXR	Wedge
401XR	X-Y	002-2126-01	002-2065-01	—	—	—	—	—	—	—
	X-Y Cartesian	002-2123-01	002-2068-01	—	—	—	—	—	—	—
	X-Z	—	101-0955-01	—	—	—	—	—	—	—
	X-Z Side Mount	002-2123-01	101-0955-01	—	—	—	—	—	—	—
402XR	X-Y	002-2130-01	002-2066-01	002-2066-01	—	—	—	—	—	—
	X-Y Cartesian	002-2069-01	002-2069-01	002-2069-01	—	—	—	—	—	—
	X-Z	—	002-2069-01	002-2069-01	—	—	—	—	—	—
	X-Z Side Mount	002-2125-01	002-2069-01	002-2069-01	—	—	—	—	—	—
404XR 404LXR	X-Y	100-9193-01	100-9193-01	100-9193-01	Direct Mount*	100-9584-01	—	—	—	100-9274-01
	X-Y Carriage to Carriage	—	—	—	100-3945-01	100-3945-01	—	—	—	—
	X-Y Cartesian Right Hand	002-2162-02	002-2162-02	002-2162-02	—	—	—	—	—	—
	X-Y Cartesian Left Hand	002-2162-02	002-2162-02	002-2162-02	—	—	—	—	—	—
	X-Z	—	—	—	002-1839-01	—	—	—	—	—
	X-Z Side Mount	—	—	—	002-1840-01	—	—	—	—	—
406XR 406LXR	X-Y	100-9194-01	100-9194-01	100-9194-01	Direct Mount*	Direct Mount*	Direct Mount*	Direct Mount*	—	100-9274-01
	X-Y Carriage to Carriage	—	—	—	100-4191-01	100-4191-01	100-4191-01	100-4191-01	—	—
	X-Y Cartesian	—	—	—	002-2163-01	002-2163-01	—	—	—	—
	X-Z	—	—	—	002-1823-01	—	002-1817-01	—	—	—
	X-Z Side Mount	—	—	—	002-1824-01	—	002-1818-01	—	—	—
412XR 412LXR	X-Y	—	—	—	Direct Mount* or Toe Clamp	Direct Mount* or Toe Clamp	Direct Mount* or Toe Clamp	Direct Mount* or Toe Clamp	100-6784-01	—
	X-Y Cartesian	—	—	—	—	—	002-2164-01	002-2164-01	—	—
ZP 200 Wedge	X-Y	—	—	—	100-9274-01	100-9274-01 or Toe Clamp	100-9274-01 or Toe Clamp	100-9274-01	—	—

* An adapter plate (100-3945-01) is required whenever the X-axis is a parallel motor mount model.
If the Y-axis is 404XR with 50 mm stroke, a special plate or toe clamp option is required.

400XR Multi Axis Configurations

These diagrams show the most popular variations of multi-axis configurations. Both standard and custom brackets are available. Standard X-Y orientation will place the X axis motor at the 6 o'clock position and the Y axis motor at the 3 o'clock position.

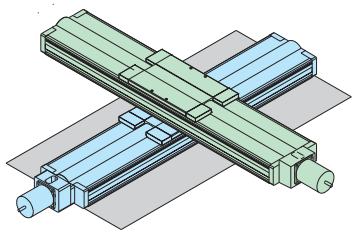


Figure 1
Two Axis (X-Y) Horizontal Mounting

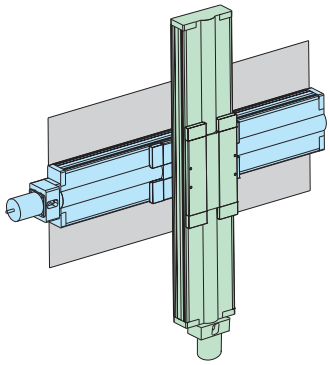


Figure 2
Two Axis (X-Z) Vertical Mounting

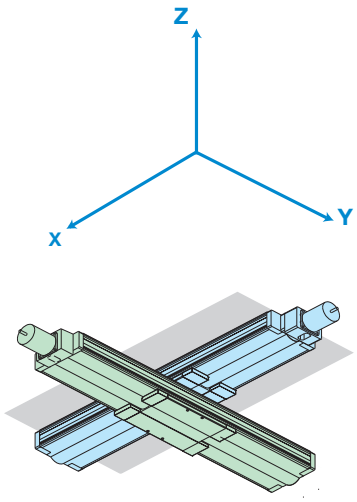


Figure 3
Two Axis (X-Y) Inverted Mounting

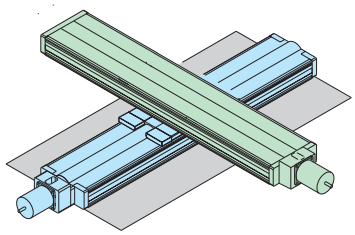


Figure 4
Two Axis-Carriage to Carriage (Y Axis Inverted)

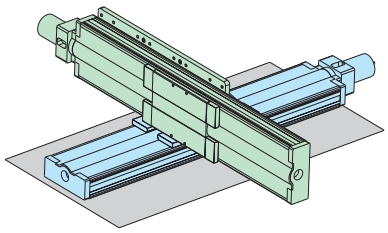


Figure 5
Two Axis (X-Y) Cartesian Horizontal Mounting

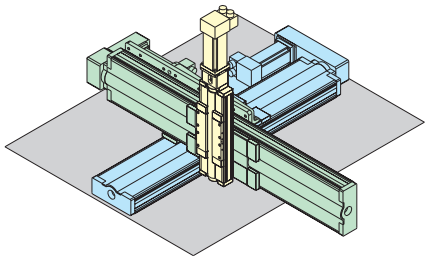


Figure 6
Three Axis (X-Y-Z) Cartesian Horizontal Mounting

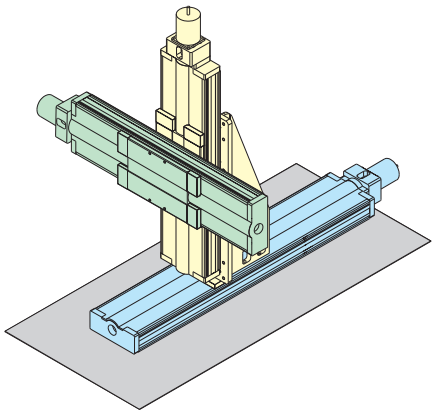


Figure 7
Three Axis (X-Z-Y) Horizontal Mounting

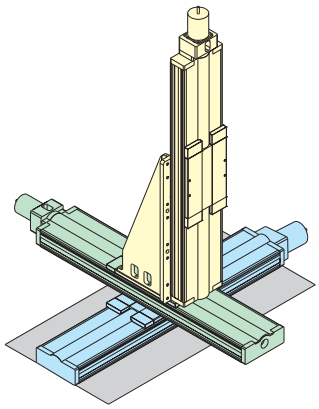


Figure 8
Three Axis (X-Y-Z) Horizontal Mounting

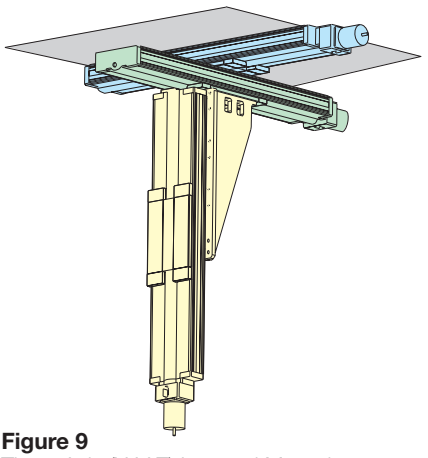
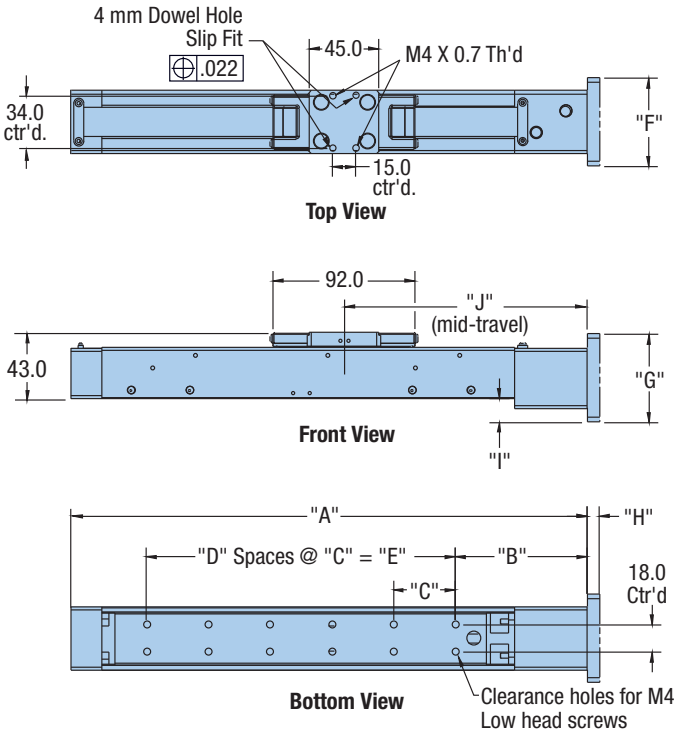


Figure 9
Three Axis (X-Y-Z) Inverted Mounting

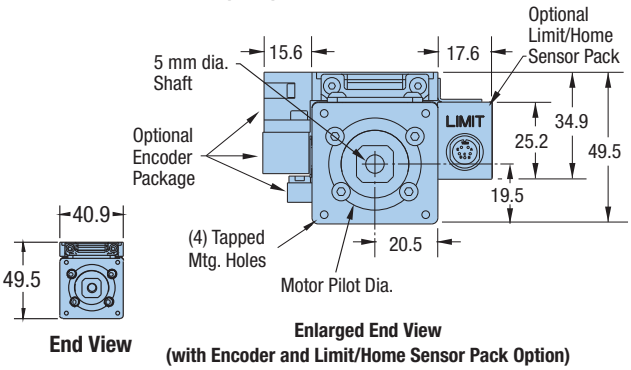
DIMENSIONS

401XR Dimensions

Download 2D & 3D files from www.parker.com/emn/401XR



Dimensions (mm)

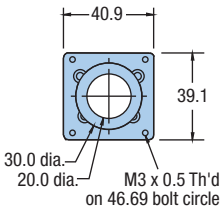


Model	Travel (mm)	Dimensions (mm) A	B	C	D	E	J
401050XR	50	209.3	82.8	80.0	1	80.0	123.0
401100XR	100	284.3	80.3	40.0	4	160.0	160.0
401150XR	150	334.3	85.3	40.0	5	200.0	185.0
401200XR	200	384.3	90.3	40.0	6	240.0	210.0
401300XR	300	509.3	92.8	40.0	9	360.0	260.0

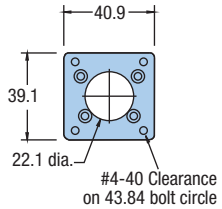
Motor Size	Order Code	Dimensions (mm) F	G	H	I
SM 16	M2	40.9	39.1	–	6.5
NEMA 23/SM 23	M3	57.2	57.2	4.0	15.6
NEMA 17	M37	40.9	39.1	–	6.5
BE 23	M61	57.2	57.2	8.0	15.6

In-Line Motor Adapters

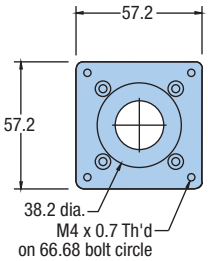
Used to easily accommodate the mounting of different servo or stepper motors.



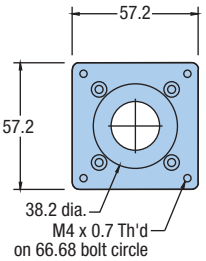
SM 16



NEMA 17



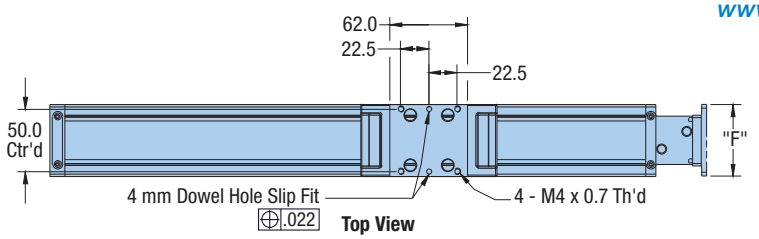
SM 23 or NEMA 23



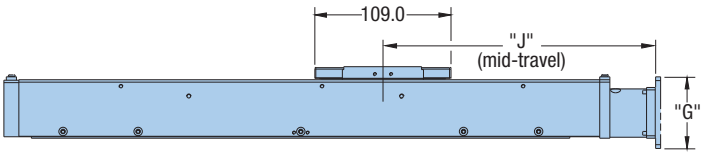
BE 23

402XR Dimensions

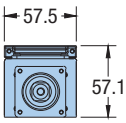
Download 2D & 3D files from www.parker.com/emn/402XR



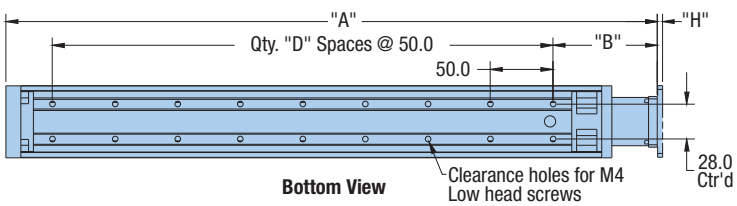
Top View



Front View

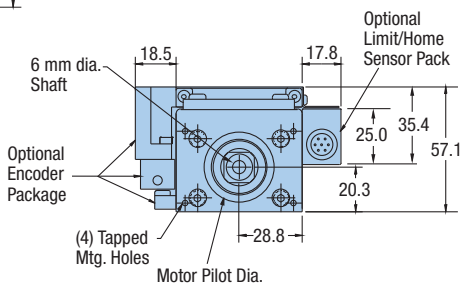


End View



Bottom View

Dimensions (mm)



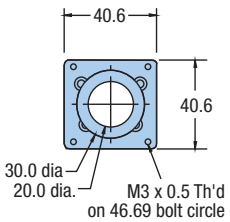
Enlarged End View
(with Encoder and Limit/Home Sensor Pack Option)

Model	Travel (mm)	Dimensions (mm) A	B	D	J
402100XR	100	320.5	83.5	4	184.0
402150XR	150	370.5	83.5	5	214.0
402200XR	200	420.5	83.5	6	234.0
402300XR	300	520.5	83.5	8	284.0
402400XR	400	620.5	83.5	10	334.0
402600XR	600	820.5	83.5	14	434.0

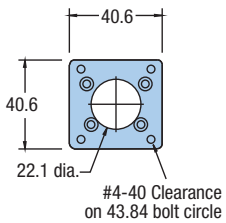
Motor Size	Order Code	Dimensions (mm) F	G	H
SM 16	M2	40.6	40.6	–
NEMA 23/SM 23	M3	57.2	57.2	4.0
NEMA 17	M37	40.6	40.6	–
BE 23	M61	57.2	57.2	8.0

In-Line Motor Adapters

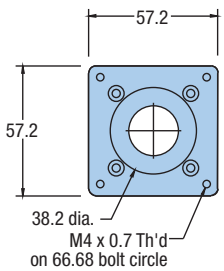
Used to easily accommodate the mounting of different servo or stepper motors.



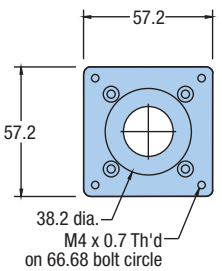
SM 16



NEMA 17



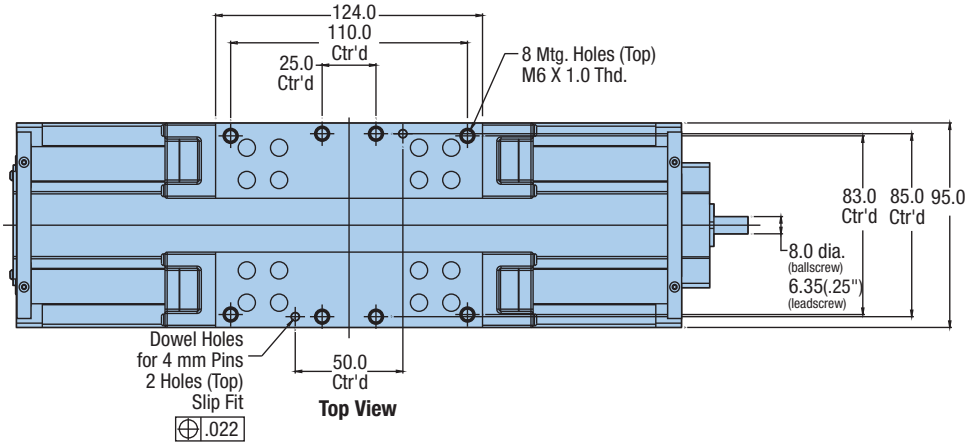
SM 23 or NEMA 23



BE 23

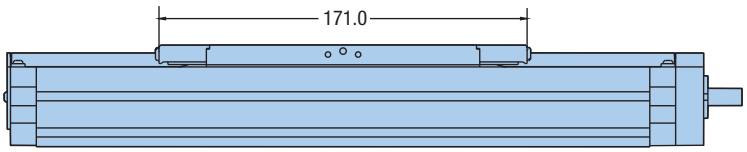
404XR Dimensions

Download 2D & 3D files from www.parker.com/emn/404XR

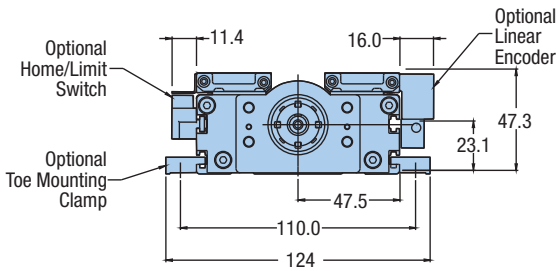


Top View

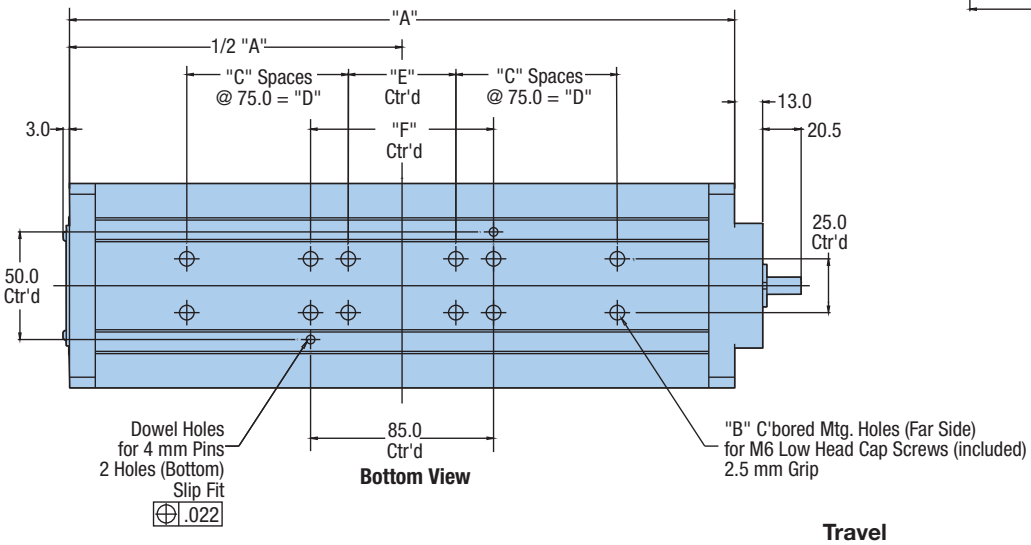
Dimensions (mm)



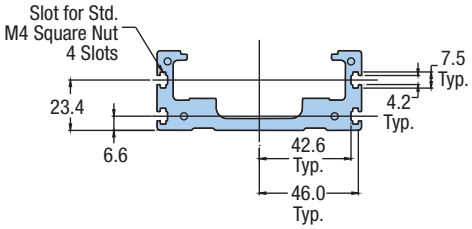
Front View



End View



Bottom View



View showing slots in extruded base

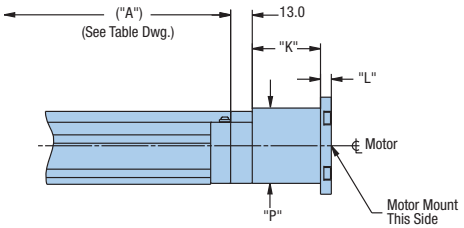
Model	Travel (mm)	Dimensions (mm) A	B	C	D	E	F
404050XR	50	259	4	–	–	–	–
404100XR	100	309	12	1	75.0	50.0	85.0
404150XR	150	359	12	1	75.0	50.0	85.0
404200XR	200	409	12	1	75.0	50.0	85.0
404250XR	250	459	16	2	150.0	50.0	85.0
404300XR	300	509	16	2	150.0	50.0	85.0
404350XR	350	559	16	2	150.0	50.0	85.0
404400XR	400	609	20	3	225.0	50.0	85.0
404450XR	450	659	20	3	225.0	50.0	85.0
404500XR	500	709	20	3	225.0	50.0	85.0
404550XR	550	759	24	4	300.0	50.0	85.0
404600XR	600	809	24	4	300.0	50.0	85.0

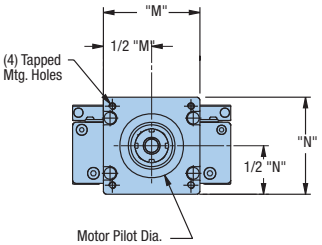
404XR Standard In-Line Motor Mounting

In-line motor mounting allows the motor to be mounted directly to the drive screw via the selected motor coupling.

Used to easily accommodate the mounting of different frame sizes. These adapter plates can be ordered separately by part number below.

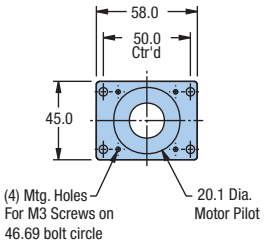
Dimensions (mm)



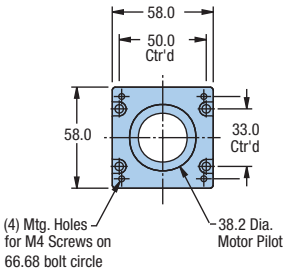


Dimensions (mm)

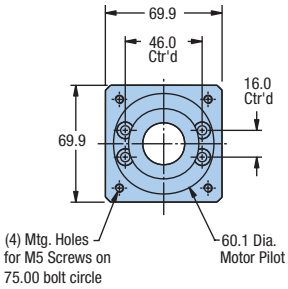
Motor Size	Order Code	Max. Motor Shaft Ø	K	L	M	N	P
SM 16	M2	9.5	41.0	4.3	53.0	45.0	45.0
NEMA 23	M3	9.5	41.0	6.5	83.0	58.0	45.0
NEMA 34	M4	9.5	41.0	12.5	83.0	83.0	45.0
NEO 70	M21	11.0	53.0	–	69.9	69.9	69.9



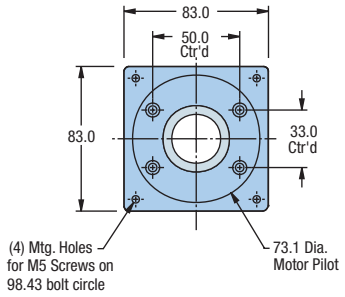
SM 16



NEMA 23



NEOMETRIC 70/SMN060



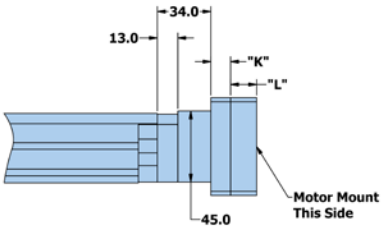
NEMA 34

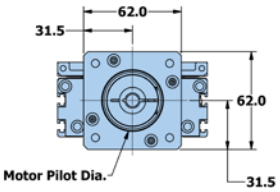
404XR Universal Motor Mounting

The new Universal Motor Adapter (UMA) makes adapting 3rd party motors to the 404XR easier than ever. The Universal Motor Adaptor option allow for the coupling of motor frame sizes from 62 mm on down, accommodating motor shaft diameters up to 16 mm. To determine if a 404XR has a mount to your preferred motor please visit **www.parker.com/emn/404XR**, and launch the online eConfigurator (note that these adapter kits establish fit to the actuator only, proper actuator sizing should still be conducted to ensure application performance).

Coupling Style	"K"
Oldham	12.5
Bellows	12.5

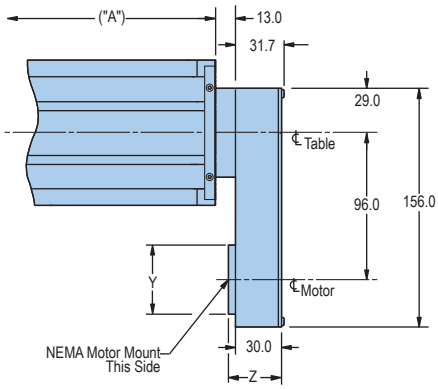
Motor Shaft Length	"L"
16 – 35	16.5
35.1 – 41	22.5



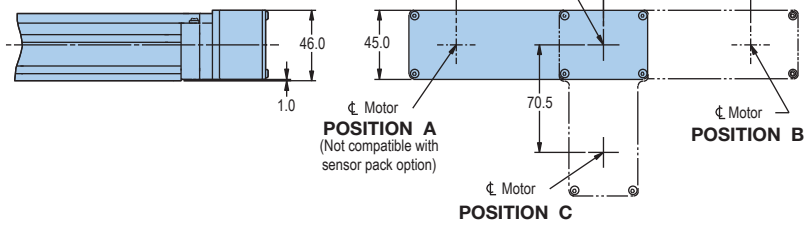


404XR Parallel Motor Mounting

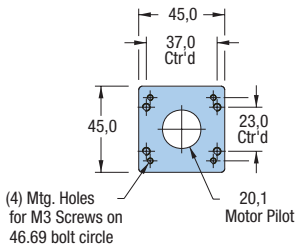
Parallel motor mounting is employed whenever a shorter overall unit length is needed. The motor is positioned along the sides or bottom of the table as designated by position A, B, or C. (No coupling required.)



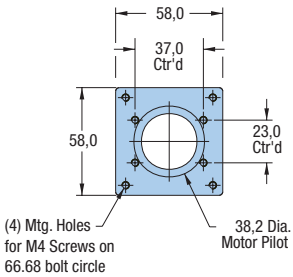
Motor Size	Dimensions Y (mm)	Z (mm)	Motor Shaft Ø
SM 16	45.0	34.5	0.250”
SM 23/BE 23	58.0	34.5	0.375”
NEMA 23	58.0	34.5	0.250”



SM 16



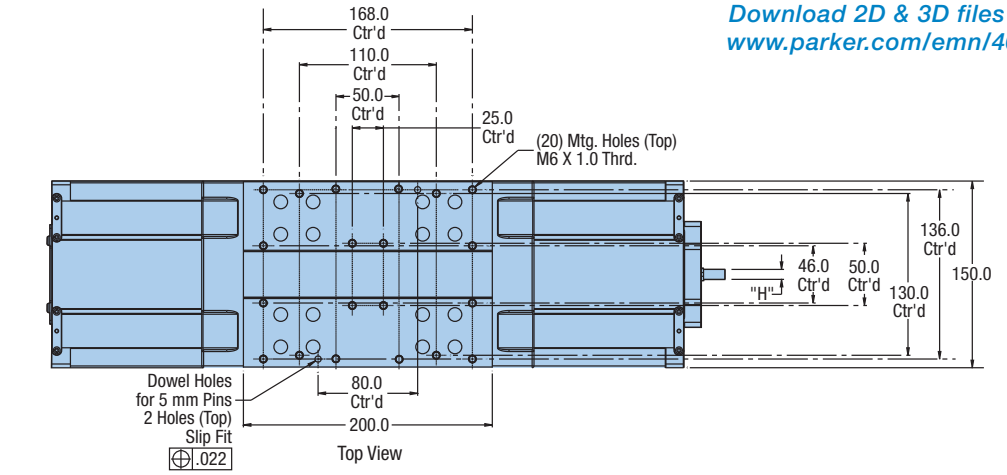
NEMA 23

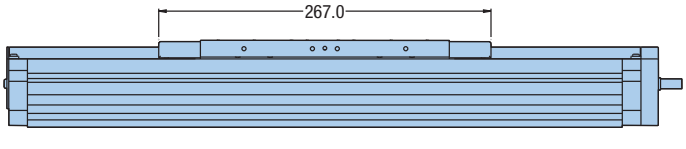


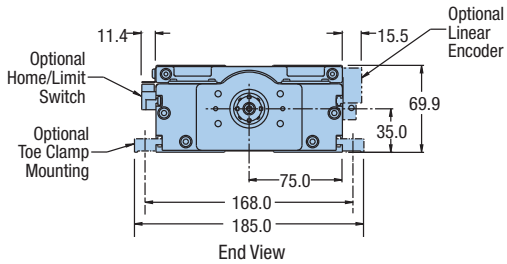
406XR Dimensions

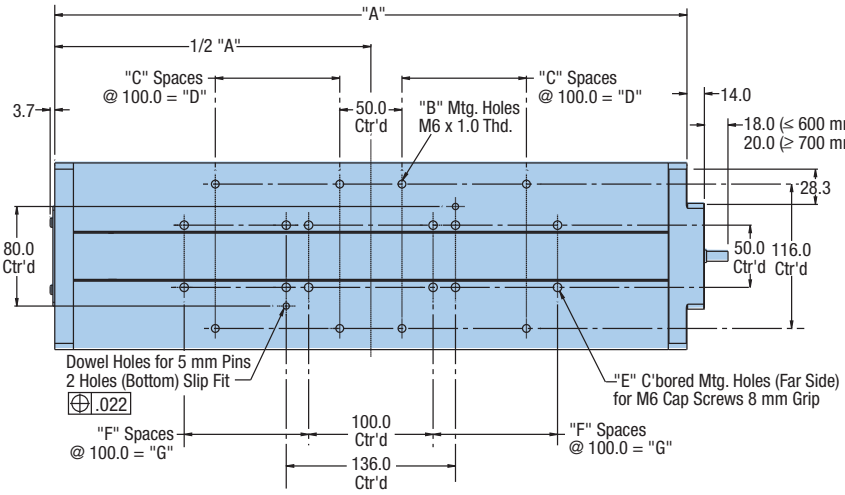
Download 2D & 3D files from www.parker.com/emn/406XR

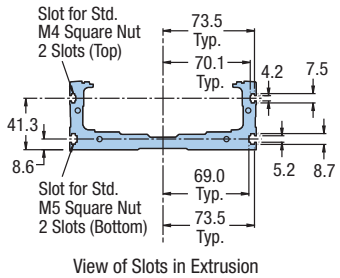
Dimensions (mm)











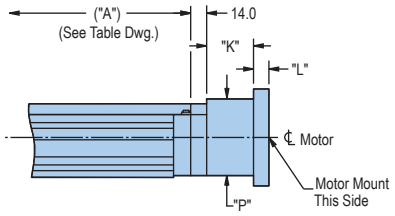
View of Slots in Extrusion

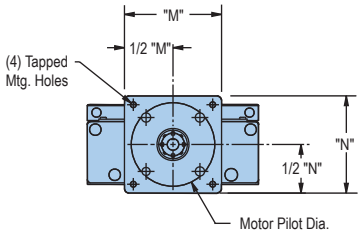
Model	Travel (mm)	Ballscrew Ø	Dimensions (mm) A	B	C	D	E	F	G	H
4060100XR	100	16	408	8	1	100.0	12	1	100.0	8.0
4060200XR	200	16	508	8	1	100.0	12	1	100.0	8.0
4060300XR	300	16	608	12	2	200.0	16	2	200.0	8.0
4060400XR	400	16	708	12	2	200.0	16	2	200.0	8.0
4060500XR	500	16	808	16	3	300.0	20	3	300.0	8.0
4060600XR	600	16	908	16	3	300.0	20	3	300.0	8.0
4060700XR	700	25	1008	20	4	400.0	24	4	400.0	10.0
4060800XR	800	25	1108	20	4	400.0	24	4	400.0	10.0
4060900XR	900	25	1208	24	5	500.0	28	5	500.0	10.0
4061000XR	1000	25	1308	24	5	500.0	28	5	500.0	10.0
4061250XR	1250	25	1558	32	7	700.0	32	6	600.0	10.0
4061500XR	1500	25	1808	36	8	800.0	40	8	800.0	10.0
4061750XR	1750	25	2058	40	9	900.0	44	9	900.0	10.0
4062000XR	2050	25	2308	44	10	1000.0	48	10	1000.0	10.0

406XR In-Line Motor Mounting

In-line motor mounting allows the motor to be mounted directly to the drive screw via the selected motor coupling.

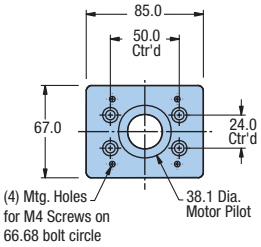
Used to easily accommodate the mounting of different frame sizes. These adapter plates can be ordered separately by part number below.



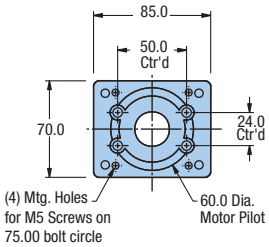


Dimensions (mm)

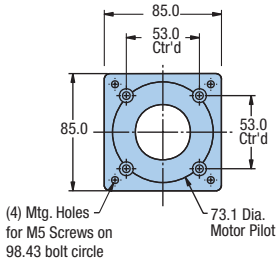
Motor Size	Order Code	Max. Motor Shaft Ø	K	L	M	N	P
MPP092	M90	16.0	53.0	12.5	92.0	92.0	69.0
NEMA 23/SM 23	M3	9.5	41.0	–	85.0	67.0	67.0
NEMA 34	M4	16.0	53.0	13.5	85.0	85.0	70.0
NEO 34	M17	16.0	53.0	13.5	85.0	85.0	70.0
NEO 70	M21	16.0	53.0	–	85.0	70.0	70.0
NEO 92	M29	16.0	53.0	12.5	92.0	92.0	70.0



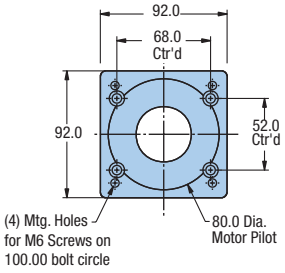
NEMA 23 or SM 23



NEO 70 / SMN060



NEMA 34 or NEO 34



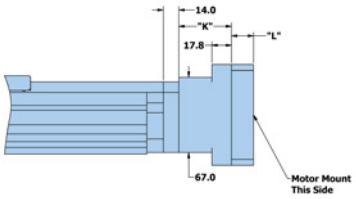
MPP092

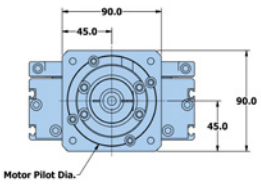
406XR Universal Motor Mounting

The new Universal Motor Adapter (UMA) makes adapting 3rd party motors to the 406XR easier than ever. The Universal Motor Adaptor option allow for the coupling of motor frame sizes from 90 mm on down, accommodating motor shaft diameters up to 20.5 mm. To determine if a 406XR has a mount to your preferred motor please visit **www.parker.com/emn/406XR,** and launch the online eConfigurator (note that these adapter kits establish fit to the actuator only, proper actuator sizing should still be conducted to ensure application performance).

Coupling Style	"K"
Oldham	35.8
Bellows	47.8

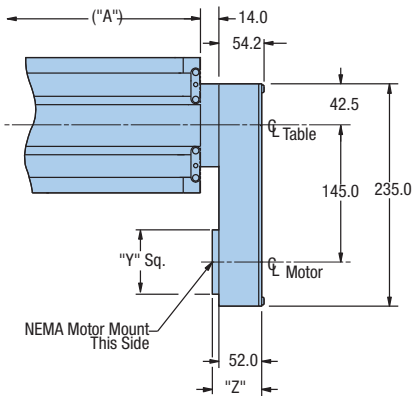
Motor Shaft Length	"L"
20 – 40	20.0
40.1 – 28.5	28.5

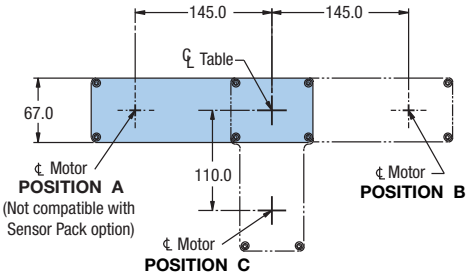




406XR Parallel Motor Mounting

Parallel motor mounting is employed whenever a shorter overall unit length is needed. The motor is positioned along the sides or bottom of the table as designated by position A, B, or C. (No coupling required.)



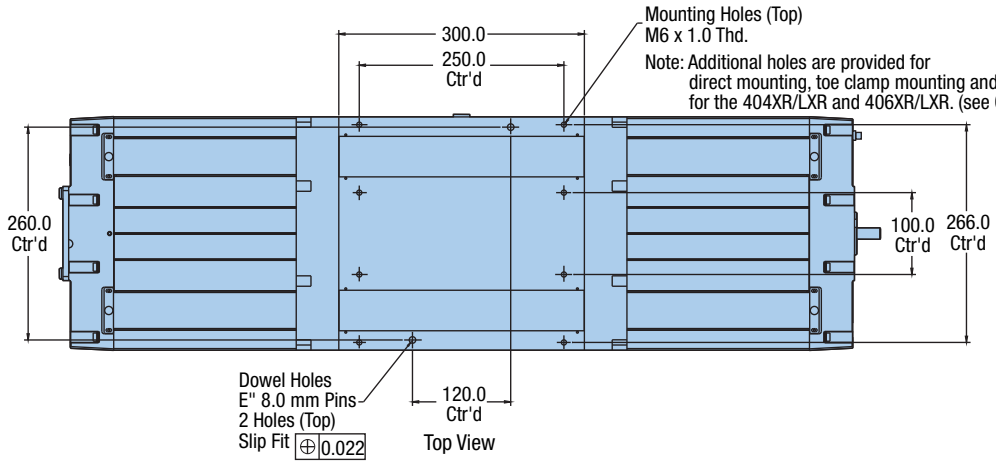


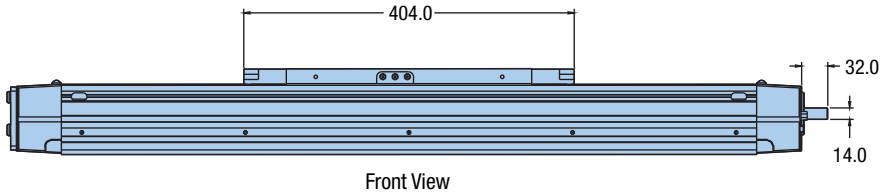
MPP092	92.0	65.7	16.0 mm
NEMA 34	83.0	62.0	0.375”
NEO 34	83.0	62.0	0.500”
NEO 70	70.0	60.0	11.0 mm
SM23/BE23	70.0	57.5	0.375”

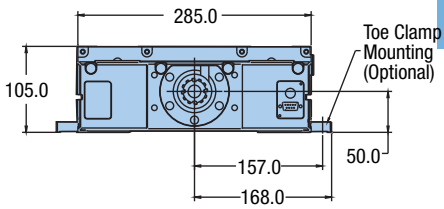
412XR Dimensions

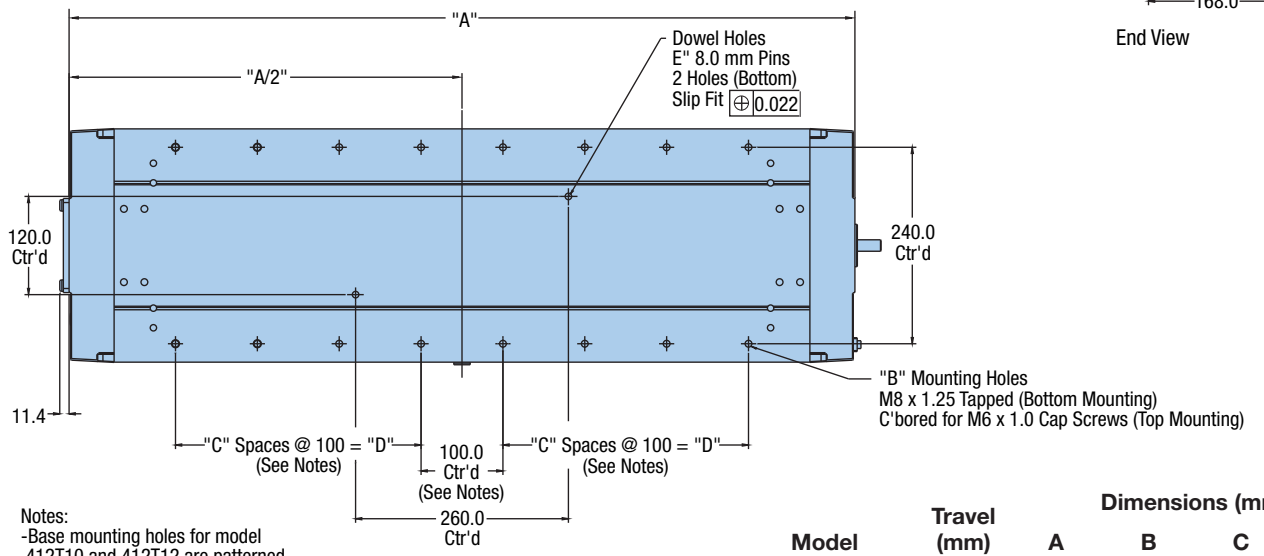
Download 2D & 3D files from www.parker.com/emn/412XR

Dimensions (mm)

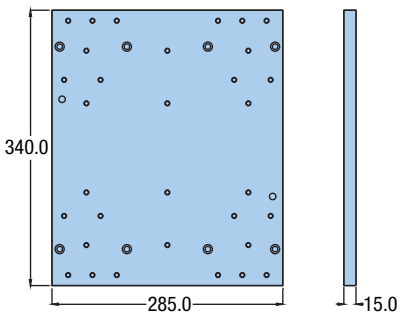








Notes:
-Base mounting holes for model 412T10 and 412T12 are patterned from one hole on centerline



X-Y Adapter Plate #100-6784
(Used to mount any 404XR, 406XR or 412XR with toe clamps)

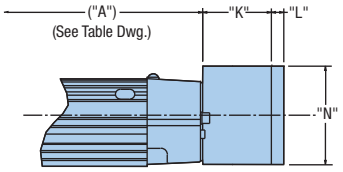
Model	Travel (mm)	Dimensions (mm) A	B	C	D
412T01	150	764	12	2	200
412T02	250	864	16	3	300
412T03	350	964	16	3	300
412T04	650	1264	24	5	500
412T05	800	1414	24	5	500
412T06	1000	1614	28	6	600
412T07	1200	1814	32	7	700
412T08	1500	2114	40	9	900
412T09	1750	2364	44	10	1000
412T10	2000	2614	50	12	1200

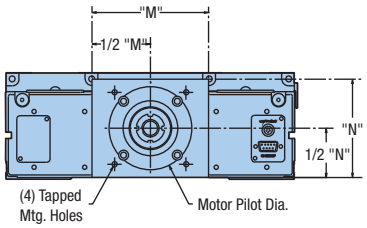
412XR In-Line Motor Mounting

In-line motor mounting allows the motor to be mounted directly to the drive screw via the selected motor coupling.

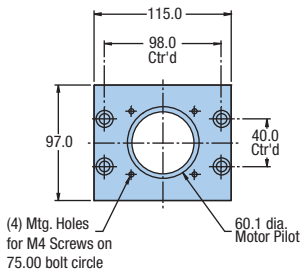
Used to easily accommodate the mounting of different frame sizes. These adapter plates can be ordered separately by part number below.

Dimensions (mm)

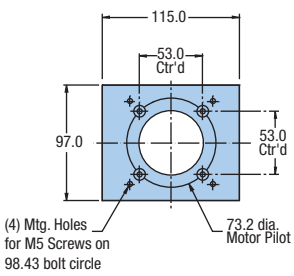




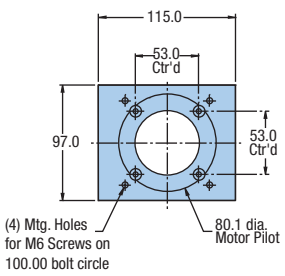
Motor Size	Order Code	Dimensions (mm) K	L	M	N
MPP092	M90	68.0	12.0	115.0	97.0
M105, SMN100	M33	100.0	–	115.0	115.0
NEMA 34	M4	68.0	12.0	115.0	97.0
NEO 34	M17	68.0	12.0	115.0	97.0
NEO 70	M21	68.0	–	115.0	97.0
NEO 92	M29	68.0	12.0	115.0	97.0



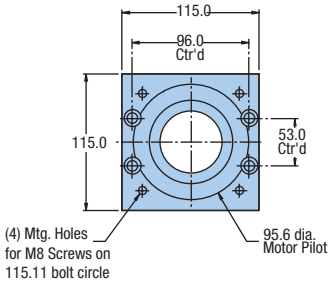
NEO 70 / SMN060



NEMA 34 or NEO 34



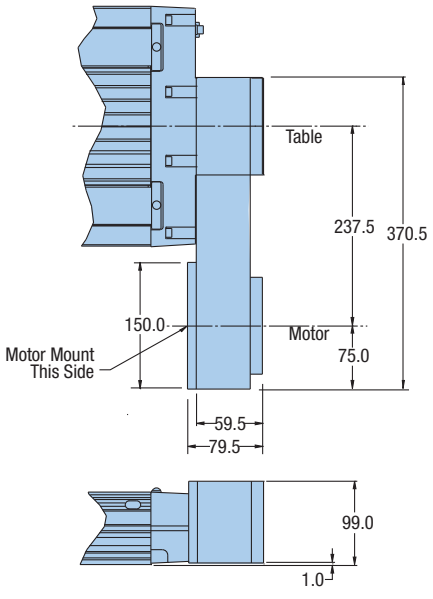
MPP092



M105 / SMN100

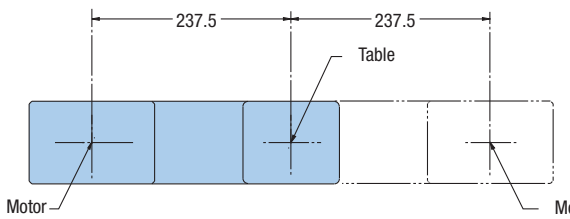
412XR Parallel Motor Mounting

Parallel motor mounting is employed whenever a shorter overall unit length is needed. The motor is positioned along the sides or bottom of the table as designated by position A, B, or C. (No coupling required.)



Dimensions

Motor Size	Bolt Circle (mm)	Pilot Ø (mm)	Shaft Ø
MPP092	100.0	80.0	16.0 mm
NEMA 34	98.4	73.2	0.375”
NEO 34	98.4	73.2	0.500”
NEO 70	75.0	60.1	11.0 mm
NEO 92	100.0	80.1	14.0 mm



POSITION A **POSITION B**

ORDERING INFORMATION

Fill in an order code from each of the numbered fields to create a complete model order code.

	①	②	③	④	⑤	⑥	⑦	⑧	⑨	⑩	⑪	⑫
Order Example:	401	100	XR	M	S	D9	H3	L2	C3	M2	E2	R1

① **Series ***
401

② **Travel – mm ***

050	50
100	100
150	150
200	200
300	300

③ **Model**

XR	Linear Table

④ **Mounting**

M	Metric

⑤ **Grade**

S	Standard
P	Precision (E3 or E4 encoder option required)

⑥ **Drive Screw ***

D3	10 mm Lead
D9	2 mm Lead

⑦ **Home Sensor ****

H1	None
H2	N.C. Current Sinking Flying Leads
H3	N.O. Current Sinking Flying Leads
H4	N.C. Current Sourcing Flying Leads
H5	N.O. Current Sourcing Flying Leads
H6	N.C. Current Sinking Locking Connector
H7	N.O. Current Sinking Locking Connector
H8	N.C. Current Sourcing Locking Connector
H9	N.O. Current Sourcing Locking Connector
H11	N.C. Current Sinking Sensor Pack
H12	N.O. Current Sinking Sensor Pack
H13	N.C. Current Sourcing Sensor Pack
H14	N.O. Current Sourcing Sensor Pack

⑧ **Limit Sensor ****

L1	None
L2	N.C. Current Sinking Flying Leads
L3	N.O. Current Sinking Flying Leads
L4	N.C. Current Sourcing Flying Leads
L5	N.O. Current Sourcing Flying Leads
L6	N.C. Current Sinking Locking Connector
L7	N.O. Current Sinking Locking Connector
L8	N.C. Current Sourcing Locking Connector
L9	N.O. Current Sourcing Locking Connector
L11	N.C. Current Sinking Sensor Pack
L12	N.O. Current Sinking Sensor Pack
L13	N.C. Current Sourcing Sensor Pack
L14	N.O. Current Sourcing Sensor Pack

⑨ **Motor Coupling**

C1	No Coupling
C2	6.3 mm (0.25 in) Bore Oldham
C3	6.3 mm (0.25 in) Bore Bellows
C5	9.5 mm (0.375 in) Bore Bellows
C24	5 mm (0.20 in) Bore Oldham
C25	5 mm (0.20 in) Bore Bellows

⑩ **Motor Mount**

M2	SM 16 In-Line Mounting
M3	NEMA 23 In-Line Mounting
M37	NEMA 17 In-Line Mounting
M61	BE 23 In-Line Mounting

⑪ **Encoder Option**

E1	None
E2	1.0 µm Resolution
E3	0.5 µm Resolution
E4	0.1 µm Resolution

⑫ **R1** Required Designator

*** Drive Screw Lead Availability**

Travel	401XR	
	2 mm	10 mm
50	•	
100	•	
150	•	
200		•
300		•

**** 50 mm stroke 401XR may only allow room for 2 sensors in sensor pack.**

	①	②	③	④	⑤	⑥	⑦	⑧	⑨	⑩	⑪	⑫
Order Example:	402	100	XR	M	S	D9	H3	L2	C3	M2	E2	R1

① **Series ***

402

② **Travel – mm ***

100	100
150	150
200	200
300	300
400	400
600	600

③ **Model**

XR	Linear Table

④ **Mounting**

M	Metric

⑤ **Grade**

S	Standard
P	Precision (E3 or E4 encoder option required)

⑥ **Drive Screw ***

D2	5 mm Lead
D3	10 mm Lead

⑦ **Home Sensor**

H1	None
H2	N.C. Current Sinking Flying Leads
H3	N.O. Current Sinking Flying Leads
H4	N.C. Current Sourcing Flying Leads
H5	N.O. Current Sourcing Flying Leads
H6	N.C. Current Sinking Locking Connector
H7	N.O. Current Sinking Locking Connector
H8	N.C. Current Sourcing Locking Connector
H9	N.O. Current Sourcing Locking Connector
H11	N.C. Current Sinking Sensor Pack
H12	N.O. Current Sinking Sensor Pack
H13	N.C. Current Sourcing Sensor Pack
H14	N.O. Current Sourcing Sensor Pack

⑧ **Limit Sensor**

L1	None
L2	N.C. Current Sinking Flying Leads
L3	N.O. Current Sinking Flying Leads
L4	N.C. Current Sourcing Flying Leads
L5	N.O. Current Sourcing Flying Leads
L6	N.C. Current Sinking Locking Connector
L7	N.O. Current Sinking Locking Connector
L8	N.C. Current Sourcing Locking Connector
L9	N.O. Current Sourcing Locking Connector
L11	N.C. Current Sinking Sensor Pack
L12	N.O. Current Sinking Sensor Pack
L13	N.C. Current Sourcing Sensor Pack
L14	N.O. Current Sourcing Sensor Pack

⑨ **Motor Coupling**

C1	No Coupling
C2	6.3 mm (0.25 in) Bore Oldham
C3	6.3 mm (0.25 in) Bore Bellows
C4	9.5 mm (0.375 in) Bore Oldham*
C5	9.5 mm (0.375 in) Bore Bellows
C24	5 mm (0.20 in) Bore Oldham
C25	5 mm (0.20 in) Bore Bellows

*NEMA 23 frame size only (M3, M61)

⑩ **Motor Mount**

M2	SM 16 In-Line Mounting
M3	NEMA 23 In-Line Mounting
M37	NEMA 17 In-Line Mounting
M61	BE 23 In-Line Mounting

⑪ **Encoder Option**

E1	None
E2	1.0 µm Resolution
E3	0.5 µm Resolution
E4	0.1 µm Resolution

⑫ **R1** Required Designator

*** Drive Screw Lead Availability**

Travel	402XR	
	5 mm	10 mm
100	•	
150	•	
200	•	
300		•
400		•
600		•

Fill in an order code from each of the numbered fields to create a complete model order code.

	①	②	③	④	⑤		⑥	⑦	⑧	⑨	⑩	⑪	⑫	⑬	⑭
Order Example:	404	450	XR	M	S	–	D33	H4	L2	C3	M4	E1	B1	R1	P1

① **Series**
404

② **Travel – mm ***

050	50 (no pinning available)
100	100
150	150
200	200
250	250
300	300
350	350
400	400
450	450
500	500
550	550
600	600

③ **Model**

XR	Linear Table

④ **Mounting**

M	Metric

⑤ **Grade**

S	Standard
P	Precision (only available with D2, D3, D4 drive screws)

⑥ **Drive Screw**

D1	Free Travel
D2	5 mm Ballscrew
D3	10 mm Ballscrew
D4	20 mm Ballscrew (standard grade only)
D31	1 mm V Thread Leadscrew
D32	2 mm V Thread Leadscrew
D33	5 mm V Thread Leadscrew
D34	0.10" V Thread Leadscrew
D35	0.10" Acme Thread Leadscrew

⑦ **Home Sensor Assembly (one sensor)**

H1	None-Free Travel (only)
H2	N.C. Current Sinking Flying Leads
H3	N.O. Current Sinking Flying Leads
H4	N.C. Current Sourcing Flying Leads
H5	N.O. Current Sourcing Flying Leads
H6	N.C. Current Sinking Locking Connector*
H7	N.O. Current Sinking Locking Connector*
H8	N.C. Current Sourcing Locking Connector*
H9	N.O. Current Sourcing Locking Connector*
H11	N.C. Current Sinking Sensor Pack**
H12	N.O. Current Sinking Sensor Pack**
H13	N.C. Current Sourcing Sensor Pack**
H14	N.O. Current Sourcing Sensor Pack**

⑧ **Travel Limit Sensor Assembly (two sensors)**

L1	None-Free Travel (only)
L2	N.C. Current Sinking Flying Leads
L3	N.O. Current Sinking Flying Leads
L4	N.C. Current Sourcing Flying Leads
L5	N.O. Current Sourcing Flying Leads
L6	N.C. Current Sinking w/Locking Connector*
L7	N.O. Current Sinking w/Locking Connector*
L8	N.C. Current Sourcing w/Locking Connector*
L9	N.O. Current Sourcing w/Locking Connector*
L11	N.C. Current Sinking Sensor Pack**
L12	N.O. Current Sinking Sensor Pack**
L13	N.C. Current Sourcing Sensor Pack**
L14	N.O. Current Sourcing Sensor Pack**

Motor Interface Option
- Standard Parker Motor Adapters (go to Standard Parker options in **blue**)

–OR–
- Universal Motor Adapter for other motors (go to Universal Motor Adapter in **grey**)

Standard Parker Motor Adapters

⑨ **Motor Coupling**

C1	No Coupling (required for parallel mounting)
C2	0.250" Oldham
C3	0.250" Bellows (required for precision grade)
C4	0.375" Oldham
C5	0.375" Bellows (required for precision grade)
C6	11 mm Oldham
C7	11 mm Bellows (required for precision grade)
C10	14 mm Oldham (M75 motor option)
C11	14 mm Bellows (M75 motor option)
C22	9 mm Oldham
C23	9 mm Bellows
C24	5 mm Oldham (M37 motor option)
C25	5 mm Bellows (M37 motor option)
C26	8 mm Oldham (M71 motor option)
C27	8 mm Bellows (M71 motor option)
C28	0.1875" Oldham (M37 motor option)
C29	0.1875" Bellows (M37 motor option)

(Motor Coupling continued next page)

* Sensors with locking connector include 5 m extension cable.
** Sensor Pack includes 3 m cable.

(Motor Coupling continued)

C30	0.250” Oldham (couplings for leadscrew grade)
C31	0.250” Bellows (couplings for leadscrew grade)
C32	0.375” Oldham (couplings for leadscrew grade)
C33	0.375” Bellows (couplings for leadscrew grade)
C39	9 mm Bellows (couplings for leadscrew grade)

Standard Parker Motor Adapters

⑩ **Motor Mount ***

M1	No Motor Mount
M2	SM 16 In-Line Mounting
M3	NEMA 23 & SM 23 In-Line Mounting
M4	NEMA 34 In-Line Mounting
M5	SM 16 Parallel Mounting, “A” Location*
M6	SM 16 Parallel Mounting, “B” Location*
M7	SM 16 Parallel Mounting, “C” Location*
M8	NEMA 23 Parallel Mounting, “A” Location*
M9	NEMA 23 Parallel Mounting, “B” Location*
M10	NEMA 23 Parallel Mounting, “C” Location*
M11	SM 23 Parallel Mounting, “A” Location*
M12	SM 23 Parallel Mounting, “B” Location*
M13	SM 23 Parallel Mounting, “C” Location*
M21	Neometric 70 In-Line Mounting
M37	NEMA 17 In-Line Mounting
M42	SM232AQ NPSN Servo Motor In-Line Mounting
M46	HV232-02-10 Stepper Motor In-Line Mounting
M49	Handcrank without Readout
M50	Handcrank with Readout (0.10” or 1 mm leads only)
M51	HDY55 In-Line Mounting
M61	BE 23 In-Line Mounting
M62	BE 23 Parallel Mounting, “A” Location*
M63	BE 23 Parallel Mounting, “B” Location*
M64	BE 23 Parallel Mounting, “C” Location*
M71	SGM01 In-Line Mounting
M72	SGM01 In-Line Mounting, “A” Location*
M73	SGM01 In-Line Mounting, “B” Location*
M74	SGM01 In-Line Mounting, “C” Location*
M75	SGM02 In-Line Mounting

* See 404XR dimensions for maximum allowable motor shaft diameter. Parallel motor mounts not available with leadscrew drives.

► **Continue to step ⑪ for Encoders in the order process.**

Universal Motor Adapter

⑨ **Motor Coupling**

BW	Bellows coupling option
OH	Oldham coupling option

⑩ **Motor Mount**

U###	Consult the online eConfigurator at **www.parker.com/emn/404XR** to create a complete part number for the desired 404XR with motor mounting to a 3rd party motor. For more details on how to use the online configurator, see page 15 of this brochure.

⑪ **Encoder Option**

E1	No Encoder
E2	1.0 µm Resolution Linear Encoder (tape scale)
E3	0.5 µm Resolution Linear Encoder (tape scale)
E4	0.1 µm Resolution Linear Encoder (tape scale)
E5	Rotary Shaft Encoder (not available with brake)

⑫ **Brake Option**

B1	No Brake
B2	Shaft Brake (Refer to 404XR holding torque specifications to confirm maximum load. Not available with rotary encoder)

⑬ **Cleanroom Preparation**

R1	Class 1000 Compatible
R2	Class 10 Compatible (consult factory)
R5	Class 1000 with Easy Lube System
R8	Class 10 with Easy Lube System

⑭ **Pinning Option ***

P1	No multi-axis pinning
P2	X axis transfer pinning to Y or Z axis - 30 arc-sec **
P3	Y axis transfer pinning to X axis - 30 arc-sec
P4	Z axis transfer pinning to X axis - 30 arc-sec
P5	X axis transfer pinning to Y axis - 125 arc-sec
P6	Y axis transfer pinning to X axis - 125 arc-sec

* Pinning option is for pinning to other 404XR and 406XR tables. Transfer pinning is not available on some XR to LXR models. Contact factory for more information. Pinning XY orientation standard with Y motor at 3 o’clock position.
** Z pinning uses bracket (see figures 7, 8 and 9 on page 18)

Fill in an order code from each of the numbered fields to create a complete model order code.

	①	②	③	④	⑤		⑥	⑦	⑧	⑨	⑩	⑪	⑫	⑬	⑭
Order Example:	406	900	XR	M	S	–	D3	H4	L1	C7	M4	E1	B1	R1	P1

① **Series**
406

② **Travel – mm ***

100	100
200	200
300	300
400	400
500	500
600	600
700	700
800	800
900	900
1000	1000
1250	1250
1500	1500
1750	1750
2000	2000

③ **Model**

XR	Linear Table

④ **Mounting**

M	Metric

⑤ **Grade ***

S	Standard
P	Precision

⑥ **Drive Screw ***

D1	Free Travel
D2	5 mm Ballscrew
D3	10 mm Ballscrew
D4	20 mm Ballscrew
D5	25 mm Ballscrew

⑦ **Home Sensor Assembly (one sensor)**

H1	None
H2	N.C. Current Sinking Flying Leads
H3	N.O. Current Sinking Flying Leads
H4	N.C. Current Sourcing Flying Leads
H5	N.O. Current Sourcing Flying Leads
H6	N.C. Current Sinking Locking Connector**
H7	N.O. Current Sinking Locking Connector**
H8	N.C. Current Sourcing Locking Connector**
H9	N.O. Current Sourcing Locking Connector**
H11	N.C. Current Sinking Sensor Pack***
H12	N.O. Current Sinking Sensor Pack***
H13	N.C. Current Sourcing Sensor Pack***
H14	N.O. Current Sourcing Sensor Pack***

⑧ **Travel Limit Sensor Assembly (two sensors)**

L1	None
L2	N.C. Current Sinking Flying Leads
L3	N.O. Current Sinking Flying Leads
L4	N.C. Current Sourcing Flying Leads
L5	N.O. Current Sourcing Flying Leads
L6	N.C. Current Sinking w/Locking Connector**
L7	N.O. Current Sinking w/Locking Connector**
L8	N.C. Current Sourcing w/Locking Connector**
L9	N.O. Current Sourcing w/Locking Connector**
L11	N.C. Current Sinking Sensor Pack ***
L12	N.O. Current Sinking Sensor Pack***
L13	N.C. Current Sourcing Sensor Pack***
L14	N.O. Current Sourcing Sensor Pack ***

*** Drive Screw Lead Availability**

Travel	Precision Grade		Standard Grade			
	5 mm	10 mm	5 mm	10 mm	20 mm	25 mm
100	•	•	•	•	•	
200	•	•	•	•	•	
400	•	•	•	•	•	
400	•	•	•	•	•	
500	•	•	•	•	•	
600	•	•	•	•	•	
700			•	•		•
800			•	•		•
900			•	•		•
1000			•	•		•
1250			•	•		•
1500			•	•		•
1750			•	•		•
2000			•	•		•

** Sensors with locking connector include 5 m extension cable.
*** Sensor Pack includes 3 m cable.

Motor Interface Option

- Standard Parker Motor Adapters (go to Standard Parker options in **blue**)

–OR–

- Universal Motor Adapter for other motors (go to Universal Motor Adapter in **grey**)

Standard Parker Motor Adapters

⑨ **Motor Coupling**

C1	No Coupling (required for parallel mounting)
C2	0.250" Oldham
C3	0.250" Bellows (required for precision grade)
C4	0.375" Oldham
C5	0.375" Bellows (required for precision grade)
C6	11 mm Oldham
C7	11 mm Bellows (required for precision grade)
C8	0.500" Oldham
C9	0.500" Bellows (required for precision grade)
C10	14 mm Oldham
C11	14 mm Bellows (required for precision grade)
C12	16 mm Oldham
C13	16 mm Bellows (required for precision grade)

⑩ **Motor Mount ***

M1	No Motor Mount
M3	NEMA 23 & SM 23 In-Line Mounting
M4	NEMA 34 In-Line Mounting
M11	SM 23 Parallel Mounting, "A" Location*
M12	SM 23 Parallel Mounting, "B" Location*
M13	SM 23 Parallel Mounting, "C" Location*
M14	NEMA 34 Parallel Mounting, "A" Location
M15	NEMA 34 Parallel Mounting, "B" Location
M16	NEMA 34 Parallel Mounting, "C" Location
M17	Neometric 34 In-Line Mounting
M18	Neometric 34 Parallel Mounting, "A" Location
M19	Neometric 34 Parallel Mounting, "B" Location
M20	Neometric 34 Parallel Mounting, "C" Location
M21	Neometric 70 In-Line Mounting
M22	Neometric 70 Parallel Mounting, "A" Location
M23	Neometric 70 Parallel Mounting, "B" Location
M25	Neometric 70 Parallel Mounting, "C" Location
M29	Neometric 92 In-Line Mounting
M61	BE 23 In-Line Mounting
M62	BE 23 Parallel Mounting, "A" Location
M63	BE 23 Parallel Mounting, "B" Location
M64	BE 23 Parallel Mounting, "C" Location
M75	SGM02 In-Line Mounting
M90	MPP092 In-Line Mounting
M91	MPP092 Parallel Mounting, "A" Location
M92	MPP092 Parallel Mounting, "B" Location
M93	MPP092 Parallel Mounting, "C" Location

* See 406XR dimensions for maximum allowable motor shaft diameter. SM 23 parallel motor mounts not available with leadscrew drives.

► **Continue to step ⑪ for Encoders in the order process.**

Universal Motor Adapter

⑨ **Motor Coupling**

BW	Bellows coupling option
OH	Oldham coupling option

⑩ **Motor Mount**

U###	Consult the online eConfigurator at **www.parker.com/emn/406XR** to create a complete part number for the desired 404XR with motor mounting to a 3rd party motor. For more details on how to use the online configurator, see page 15 of this brochure.

⑪ **Encoder Option**

E1	No Encoder
E2	1.0 µm Resolution Linear Encoder (tape scale)
E3	0.5 µm Resolution Linear Encoder (tape scale)
E4	0.1 µm Resolution Linear Encoder (tape scale)
E5	Rotary Shaft Encoder (not available with brake)

⑫ **Brake Option**

B1	No Brake
B2	Shaft Brake (Refer to 406XR holding torque specifications to confirm maximum load. Not available with rotary encoder)

⑬ **Cleanroom Preparation**

R1	Class 1000 Compatible
R2	Class 10 Compatible (consult factory)
R5	Class 1000 with Easy Lube System
R8	Class 10 with Easy Lube System

⑭ **Pinning Option ***

P1	No multi-axis pinning
P2	X axis transfer pinning to Y or Z axis - 30 arc-sec **
P3	Y axis transfer pinning to X axis - 30 arc-sec
P4	Z axis transfer pinning to X axis - 30 arc-sec

* Pinning option is for pinning to other 404XR and 406XR tables. Transfer pinning is not available on some XR to LXR models. Contact factory for more information. Pinning XY orientation standard with Y motor at 3 o'clock position.
** Z pinning uses bracket (see figures 7, 8 and 9 on page 18)

Fill in an order code from each of the numbered fields to create a complete model order code.

	①	②	③	④	⑤		⑥	⑦	⑧	⑨	⑩	⑪	⑫	⑬	⑭
Order Example:	412	T03	XR	M	S	–	D2	H3	L3	C15	M4	E3	B1	R1	P1

① **Series**
412

② **Travel – mm**

T01	150
T02	250
T03	350
T04	650
T05	800
T06	1000
T07	1200
T08	1500
T09	1750
T10	2000

③ **Model**

XR	Linear Table

④ **Mounting**

M	Metric

⑤ **Grade**

S	Standard

⑥ **Drive Screw**

D1	Free Travel
D2	5 mm Leadscrew
D3	10 mm Leadscrew
D5	25 mm Leadscrew
D6	32 mm Leadscrew

⑦ **Home Sensor ***

H1	None
H2	N.C. Current Sinking Flying Leads
H3	N.O. Current Sinking Flying Leads
H4	N.C. Current Sourcing Flying Leads
H5	N.O. Current Sourcing Flying Leads

* Includes a 3 meter extension cable with flying lead termination. A 7.5 meter extension cable can be ordered separately.

⑧ **Travel Limit Sensor ***

L1	None
L2	N.C. Current Sinking Flying Leads
L3	N.O. Current Sinking Flying Leads
L4	N.C. Current Sourcing Flying Leads
L5	N.O. Current Sourcing Flying Leads

* Includes a 3 meter extension cable with flying lead termination. A 7.5 meter extension cable can be ordered separately.

⑨ **Motor Coupling**

C1	No Coupling
C4	0.375” Oldham
C5	0.375” Bellows
C6	11 mm Oldham
C7	11 mm Bellows
C8	0.500” Oldham
C9	0.500” Bellows
C10	14 mm Oldham
C11	14 mm Bellows
C12	16 mm Oldham
C13	16 mm Bellows
C14	0.750” (19 mm) Oldham
C15	0.750” (19 mm) Bellows

⑩ Motor Mount

M1	No Motor Mount
M4	NEMA 34 In-Line Mounting
M14	NEMA 34 Parallel Mounting, “A” Location
M15	NEMA 34 Parallel Mounting, “B” Location
M17	Neometric 34 In-Line Mounting
M18	Neometric 34 Parallel Mounting, “A” Location
M19	Neometric 34 Parallel Mounting, “B” Location
M21	Neometric 70 In-Line Mounting
M22	Neometric 70 Parallel Mounting, “A” Location
M23	Neometric 70 Parallel Mounting, “B” Location
M29	Neometric 92 In-Line Mounting
M30	Neometric 92 Parallel Mounting, “A” Location
M31	Neometric 92 Parallel Mounting, “B” Location
M33	M105 & SMN100 In-Line Mounting
M90	MPP092 In-Line Mounting
M91	MPP092 Parallel Mounting, “A” Location
M92	MPP092 Parallel Mounting, “B” Location
M93	MPP092 Parallel Mounting, “C” Location

⑪ Encoder Option

E1	No Encoder
E2	1.0 µm Resolution Linear Encoder (tape scale)
E3	0.5 µm Resolution Linear Encoder (tape scale)
E4	0.1 µm Resolution Linear Encoder (tape scale)
E5	5.0 µm Resolution Linear Encoder (tape scale)
E6	Rotary Shaft Encoder (not available with brake)
E7	Sine Encoder

⑫ Brake Option

B1	No Brake
B2	Shaft Brake (Refer to 412XR holding torque specifications to confirm maximum load. Not available with rotary encoder)

⑬ Cleanroom Preparation

R1	Class 1000 with Strip Seals
R2	Class 100 without Strip Seals

⑭ Pinning Option *

P1	No multi-axis pinning
P2	X axis transfer pinning to Y or Z axis - 30 arc-sec **
P3	Y axis transfer pinning to X axis - 30 arc-sec (includes a required 15 mm thick adapter)
P4	Z axis transfer pinning to X axis - 30 arc-sec

* Pinning option is for pinning to other 404XR and 406XR tables. Transfer pinning is not available on some XR to LXR models. Contact factory for more information. Pinning XY orientation standard with Y motor at 3 o’clock position.
** Z pinning uses bracket (see figures 7, 8 and 9 on page 18)

Looking for Precision and Dynamic Performance?

LXR Series Precision Linear Motor-Driven Positioners

http://bit.ly/AT_LXR

The 400LXR Series linear servo motor tables offer high acceleration, velocity, and precision with quick settling for superior throughput. Optimum performance is achieved by combining slotless linear motor technology with performance-matched feedback and mechanical elements.

Offered in three widths that complement the XR with a myriad of options, the 400LXR Series can solve most high-performance applications.

- **Incremental standard lengths from 50 mm to 3 m**
- **Load capacity to 9310 N**
- **5g acceleration**
- **Velocity up to 3 m/s**
- **Continuous force to 355 N, peak force to 1000 N**
- **±1 µm repeatability**
- **100% certification of precision with test reports in every shipment**
- **Cleanroom preparation**
- **Easy multi-axis configuration**
- **Pre-engineered, low-profile, modular cable management**
- **Proven IP30 strip-seal protection**
- **Encoder resolutions to 0.1 µm**
- **Fast settling**
- **Dowel holes provided for precise payload and multi-axis mounting**

Complete Robotic System Solutions

XRS Cartesian Robot Systems

Parker XRS Series "standard" Cartesian robot modules are the ideal solution for cost effective automation in life sciences, semiconductor, electronics, automated assembly, dispensing, and many other applications.

Standard XRS Systems are pre-engineered to optimize work-space, simplify selection, shorten delivery and lower costs.

Scalability

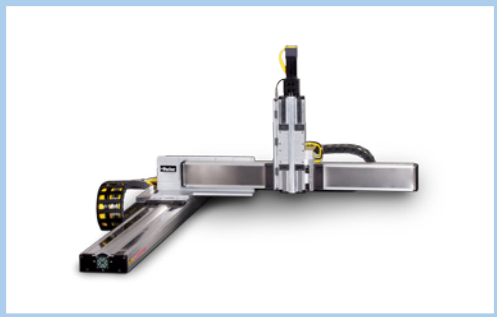
With 3 size platforms and 124 standard systems you can find a standard solution for your application.

Technology

A unique mix of linear servo motor and ballscrew drive technology provides optimized dynamic performance for today's demanding automation applications.

Reliability

XRS Systems are built from Parker's XR/LXR linear positioners, time tested and proven in thousands of applications worldwide.



http://bit.ly/AT_XRS

Small Platform XRS Cartesian Systems

- Smaller footprint for light loads and shorter travels
- Maximum X-Y work area: 600 mm X 300 mm
- Maximum load: 5 kg

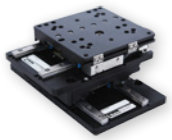
Medium Platform XRS Cartesian Systems

- For mid-range loads and travels
- Maximum X-Y work area: 1000 mm X 600 mm
- Maximum load: 12 kg

Large Platform XRS Cartesian Systems

- For heavier loads and travels
- Maximum X-Y work area: 1000 mm X 1000 mm
- Maximum load: 25 kg

Full Range of Positioning Solutions from Parker

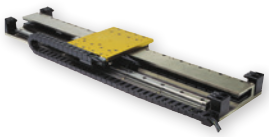


mSR Series

The mSR series positioner is the most accurate standard positioner ever offered by Parker, delivering submicron level precision in two form factors. The mSR offers OEMs high precision motion in an ultra small package.

MX Series

Designed to meet decreasing size requirements, the MX is one of the smallest linear servo motor and screw-driven positioners in the industry. Loaded with high performance features, the MX redefines "high-throughput automation" for 24/7 production demands.



T Series

Delivering high performance with economy, Trilogy positioners offer design flexibility that accommodates customization. Trilogy uses ironless linear motor technology in a pre-engineered, easily integrated, ready-to-run package.

HMR Series

The HMR has enormous moment and payload capacity. Ideal for flexibility and simplified machine integration, the HMR is one of the most user friendly and versatile lines of linear actuators on the market today.

ETH Series

The next generation of electric thrust cylinder, the ETH offers greatly improved thrust capacity and superior application optimization. High mechanical and energy efficiency reduces costs relative to fluid power systems.

ETT Series

The ETT offers a unique solution for high speed, high acceleration, and dynamic positioning capabilities. Linear motor technology delivers enhanced performance, smaller overall size, and reduced system cost and maintenance.

XE Series

Highly accurate and cost-effective, the XE combines versatility and rugged steel body construction for significant force-per-dollar value. The economical XE easily integrates into multi-axis designs.

LCR Series

The LCR delivers significant ROI through off-the-shelf simplicity combined with tailor-made fit. Reduced machine design time and complexity plus unmatched flexibility make the LCR an ideal choice for many applications.

OSP-E Series

Flexible and value-priced for medium capacity applications, the OSP-E balances cost and performance. The OSP-E delivers a simplified conversion from pneumatic to electromechanical operation.

Offer of Sale

The items described in this document and other documents or descriptions provided by Parker, its subsidiaries and its authorized distributors are hereby offered for sale at prices to be established by Parker Hannifin Corporation, its subsidiaries and its authorized distributors. This offer and its acceptance by any customer ("Buyer") shall be governed by all of the following Terms and Conditions. Buyer's order for any such item, when communicated to Parker, its subsidiary or an authorized distributor ("Seller") verbally or in writing, shall constitute acceptance of this offer.

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2. Payment: Payment shall be made by Buyer net 30 days from the date of delivery of the items purchased hereunder. Amounts not timely paid shall bear interest at the maximum rate permitted by law for each month or portion thereof that the Buyer is late in making payment. Any claims by Buyer for omissions or shortages in a shipment shall be waived unless Seller receives notice thereof within 30 days after Buyer's receipt of the shipment.

3. Delivery: Unless otherwise provided on the face hereof, delivery shall be made F.O.B. Seller's plant. Regardless of the method of delivery, however, risk of loss shall pass to Buyer upon Seller's delivery to a carrier. Any delivery dates shown are approximate only and Seller shall have no liability for any delays in delivery.

4. Warranty: Seller warrants that the items sold hereunder shall be free from defects in material or workmanship for a period of 12 months from date of shipment from Parker. THIS WARRANTY COMPRISES THE SOLE AND ENTIRE WARRANTY PERTAINING TO ITEMS PROVIDED HEREUNDER. SELLER MAKES NO OTHER WARRANTY, GUARANTEE, OR REPRESENTATION OF ANY KIND WHATSOEVER. ALL OTHER WARRANTIES, INCLUDING BUT NOT LIMITED TO, MERCHANTABILITY AND FITNESS FOR PURPOSE, WHETHER EXPRESS, IMPLIED, OR ARISING BY OPERATION OF LAW, TRADE USAGE, OR COURSE OF DEALING ARE HEREBY DISCLAIMED. NOTWITHSTANDING THE FOREGOING, THERE ARE NO WARRANTIES WHATSOEVER ON ITEMS BUILT OR ACQUIRED WHOLLY OR PARTIALLY, TO BUYER'S DESIGNS OR SPECIFICATIONS.

5. Limitation of Remedy: SELLER'S LIABILITY ARISING FROM OR IN ANY WAY CONNECTED WITH THE ITEMS SOLD OR THIS CONTRACT SHALL BE LIMITED EXCLUSIVELY TO REPAIR OR REPLACEMENT OF THE ITEMS SOLD OR REFUND OF THE PURCHASE PRICE PAID BY BUYER, AT SELLER'S SOLE OPTION. IN NO EVENT SHALL SELLER BE LIABLE FOR ANY INCIDENTAL, CONSEQUENTIAL OR SPECIAL DAMAGES OF ANY KIND OR NATURE WHATSOEVER, INCLUDING BUT NOT LIMITED TO LOST PROFITS ARISING FROM OR IN ANY WAY CONNECTED WITH THIS AGREEMENT OR ITEMS SOLD HEREUNDER, WHETHER ALLEGED TO ARISE FORM BREACH OF CONTRACT, EXPRESS OR IMPLIED WARRANTY, OR IN TORT, INCLUDING WITHOUT LIMITATION, NEGLIGENCE, FAILURE TO WARN OR STRICT LIABILITY.

6. Changes, Reschedules and Cancellations: Buyers may request to modify the designs or specifications for the items sold hereunder as well as the quantities and delivery dates thereof, or may request to cancel all or part of this order, however, no such requested modification or cancellation shall become part of the contract between Buyer and Seller unless accepted by Seller in a written amendment to this Agreement. Acceptance of any such requested modification of cancellation shall be at Seller's discretion, and shall be upon such terms and conditions as Seller may require.

7. Special Tooling: A tooling charge may be imposed for any special tooling, including without limitation, dies, fixtures, molds and patterns, acquired to manufacture items sold pursuant to this contract. Such special tooling shall be and remain Seller's property notwithstanding payment of any charges by Buyer. In no event will Buyer acquire any interest in apparatus belonging to Seller which is utilized in the manufacture of the items sold hereunder, even if such apparatus has been specially converted or adapted for such manufacture and not withstanding any charges paid by Buyer. Unless otherwise agreed, Seller shall have the right to alter, discard or otherwise dispose of any special tooling or other property in its sole discretion at any time.

8. Buyer's Property: Any designs, tools, patterns, materials, drawings confidential information or equipment furnished by Buyer, or any other items which become Buyer's property, may be considered obsolete and may be destroyed by Seller after two (2) consecutive years have elapsed without Buyer placing an order for the items which are manufactured using such property. Seller shall not be responsible for any loss or damage to such property while it is in Seller's possession or control.

9. Taxes: Unless otherwise indicated on the face hereof, all prices and charges are exclusive of excise, sales, use, property, occupational or like taxes which may be imposed by any taxing authority upon the manufacture, sale or delivery of the items sold hereunder. If any such taxes must be paid by Seller or if Seller is liable for the collection of such tax, the amount thereof shall be in addition to the amounts for the items sold. Buyer agrees to pay all such taxes or to reimburse Seller therefore upon receipt of its invoice. If Buyer claims exemption from any sales, use or other tax imposed by any taxing authority, Buyer shall save Seller harmless from and against any such tax, together with any interest or penalties thereon which may be assessed if the items are held to be taxable.

10. Indemnity For Infringement of Intellectual Property Rights: Seller shall have no liability for infringement of any patents, trademarks, copyrights, trade dress, trade secrets or similar rights except as provided in this Part 10. Seller will defend and indemnify Buyer against allegations of infringement of U.S. patents, U.S. trademarks, copyrights, trade dress and trade secrets (hereinafter 'Intellectual Property Rights'). Seller will defend at its expense and will pay the cost of any settlement or damages awarded in an action brought against Buyer based on an allegation that an item sold pursuant to this contract infringes the Intellectual Property Rights of a third party. Seller's obligation to defend and indemnify Buyer is contingent on Buyer notifying Seller within ten (10) days after Buyer becomes aware of such allegations of infringement, and Seller having sole control over the defense of any allegations or actions including all negotiations for settlement or compromise. If an item sold hereunder is subject to a claim that it infringes the Intellectual Property Rights of a third party, Seller may, at its sole expense and option, procure for Buyer the right to continue using said item, replace or modify said item so as to make it non infringing, or offer to accept return of said item and return the purchase price less a reasonable allowance for depreciation. Notwithstanding the foregoing, Seller shall have no liability for claims of infringement based on information provided by Buyer, or directed to items delivered hereunder for which the designs are specified in whole or part by Buyer, or infringements resulting from the modification, combination or use in a system of any item sold hereunder. The foregoing provisions of this Part 10 shall constitute Seller's sole and exclusive liability and Buyer's sole and exclusive remedy for infringement of Intellectual Property Right. If a claim is based on information provided by Buyer or if the design for an item delivered hereunder is specified in whole or in part by Buyer, Buyer shall defend and indemnify Seller for all costs, expenses or judgments resulting from any claim that such item infringes any patent, trademark, copyright, trade dress, trade secret or any similar right.

11. Force Majeure: Seller does not assume the risk of and shall not be liable for delay or failure to perform any of Seller's obligations by reason of circumstances beyond the reasonable control of Seller (hereinafter 'Events of Force Majeure'). Events of Force Majeure shall include without limitation, accidents, acts of God, strikes or labor disputes, acts, laws, rules or regulations of any government or government agency, fires, floods, delays or failures in delivery of carriers or suppliers, shortages of materials and any other cause beyond Seller's control.

12. Entire Agreement/Governing Law: The terms and conditions set forth herein, together with any amendments, modifications and any different terms or conditions expressly accepted by Seller in writing, shall constitute the entire Agreement concerning the items sold, and there are no oral or other representations or agreements which pertain thereto. This Agreement shall be governed in all respects by the law of the State of Ohio. No actions arising out of the sale of the items sold hereunder of this Agreement may be brought by either party more than two (2) years after the cause of action accrues.

⚠ WARNING

FAILURE OR IMPROPER SELECTION OR IMPROPER USE OF THE PRODUCTS AND/OR SYSTEMS DESCRIBED HEREIN OR RELATED ITEMS CAN CAUSE DEATH, PERSONAL INJURY AND PROPERTY DAMAGE.

This document and other information from Parker Hannifin Corporation, its subsidiaries and authorized distributors provide product and/or system options for further investigation by users having technical expertise. It is important that you analyze all aspects of your application and review the information concerning the product or system in the current product catalog. Due to the variety of operating conditions and applications for these products or systems, the user, through its own analysis and testing, is solely responsible for making the final selection of the products and systems and assuring that all performance, safety and warning requirements of the application are met.

The products described herein, including without limitation, product features, specifications, designs, availability and pricing, are subject to change by Parker Hannifin Corporation and its subsidiaries at any time without notice.

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Fax: 52-722-279-0316

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Parker Hannifin Electromechanical Automation Division
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800-245-6903
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Email: emn_support@parker.com

XR Series:
Made in the USA

8.31.16

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